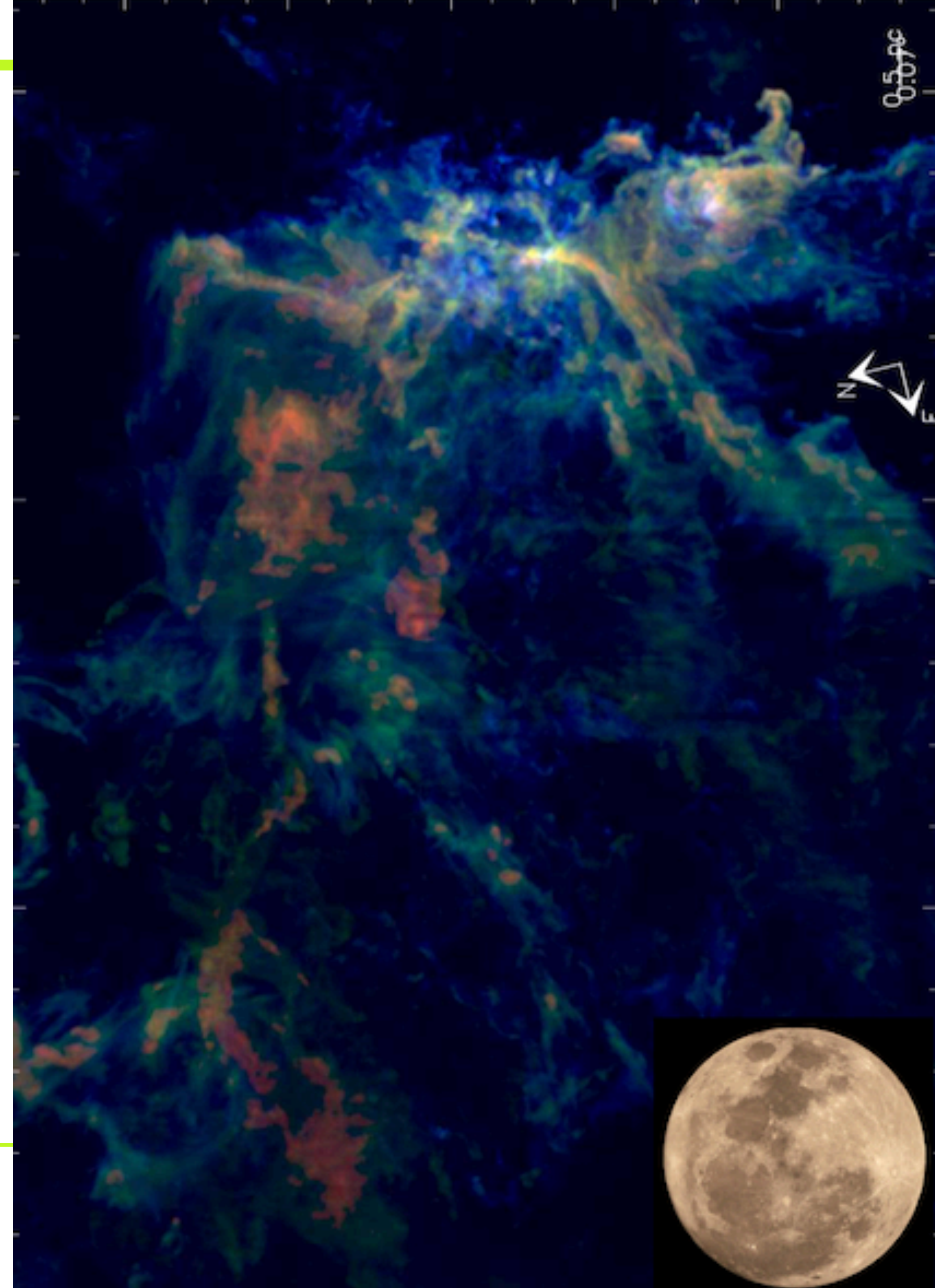


Inferring physical conditions in star forming regions with new Bayesian approach and spatial regularization

P. Palud, F. Le Petit, E. Bron, P. Chainais,
P.-A. Thouvenin, consortium Orion B



Point of the presentation

Effect of **radiative feedback** on parent cloud



Efficient estimation of **physical conditions**
in **star forming region**



Carina nebula



Pillars of creation

Example: the OrionB cloud

Source: IRAM-30m, J.Pety, M. Guerin, consortium Orion-B

Observations led by **OrionB Consortium**,
(Pety et al., 2016)

Very rich dataset!

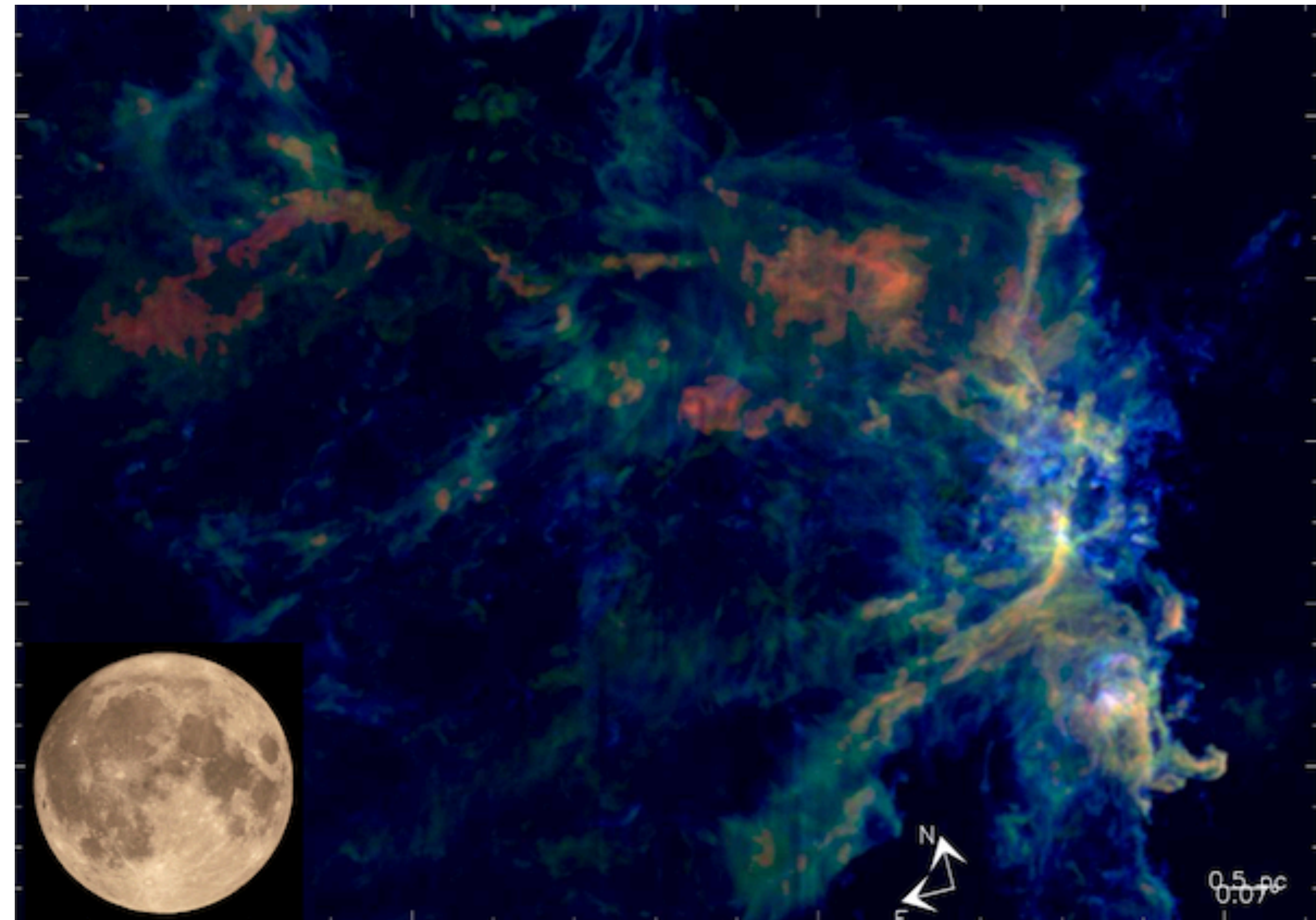
$\simeq 10^6$ pixels

$\simeq 100 \text{ pc}^2$
tens of lines

Great variations of SNR

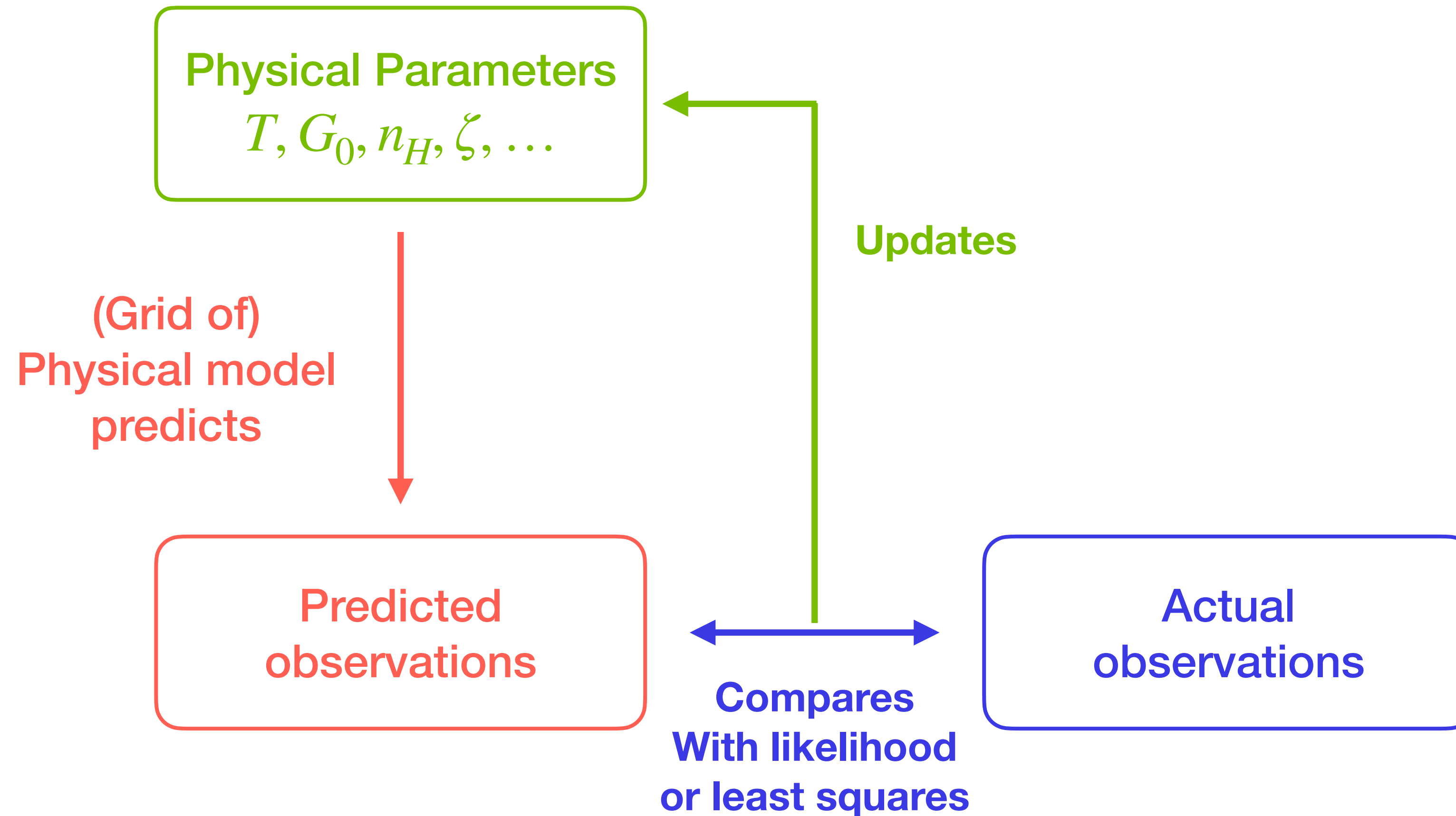
\implies Between pixels

\implies Between lines



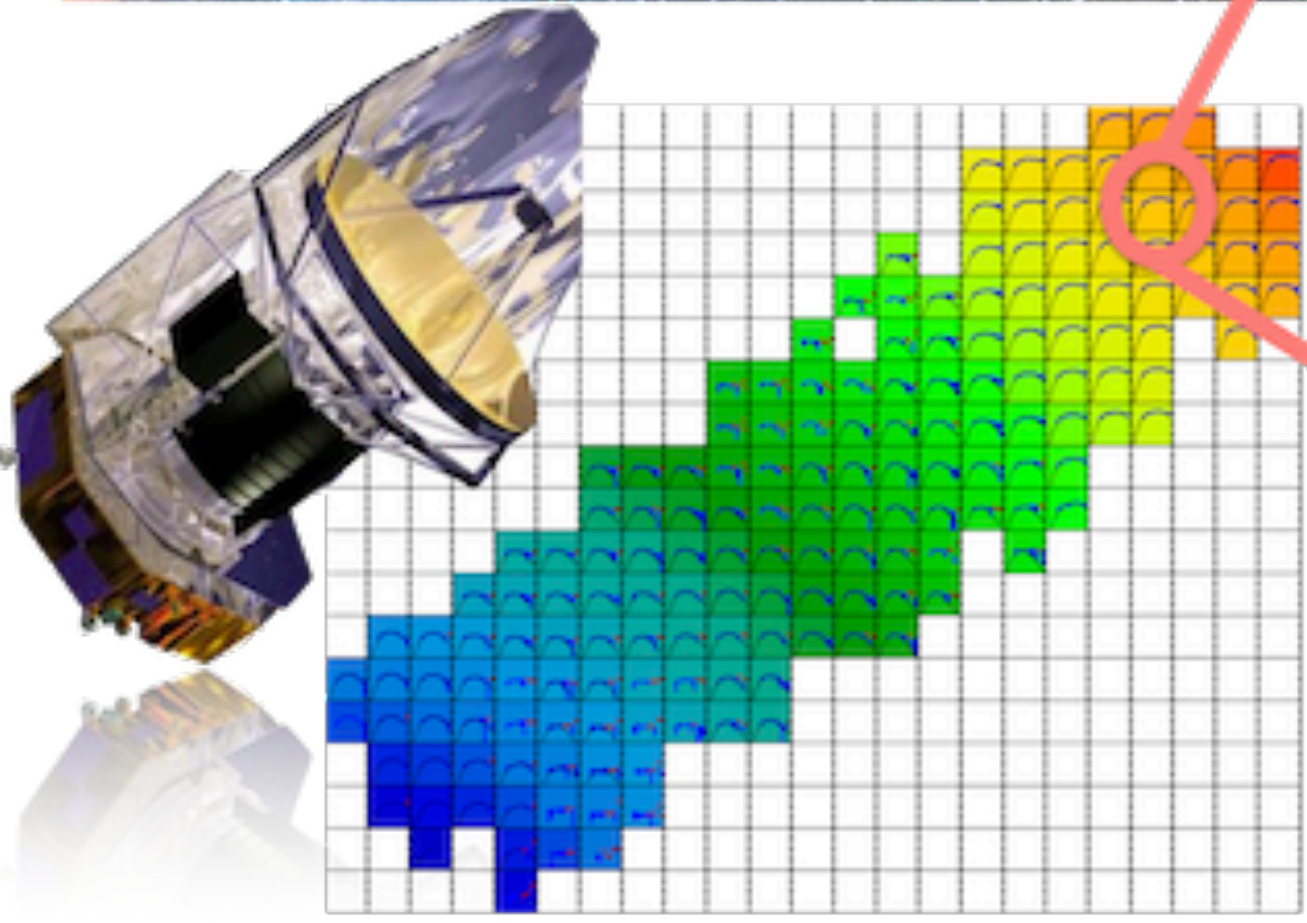
Estimation procedure

observations = Integrated intensities
of molecular / atomic lines

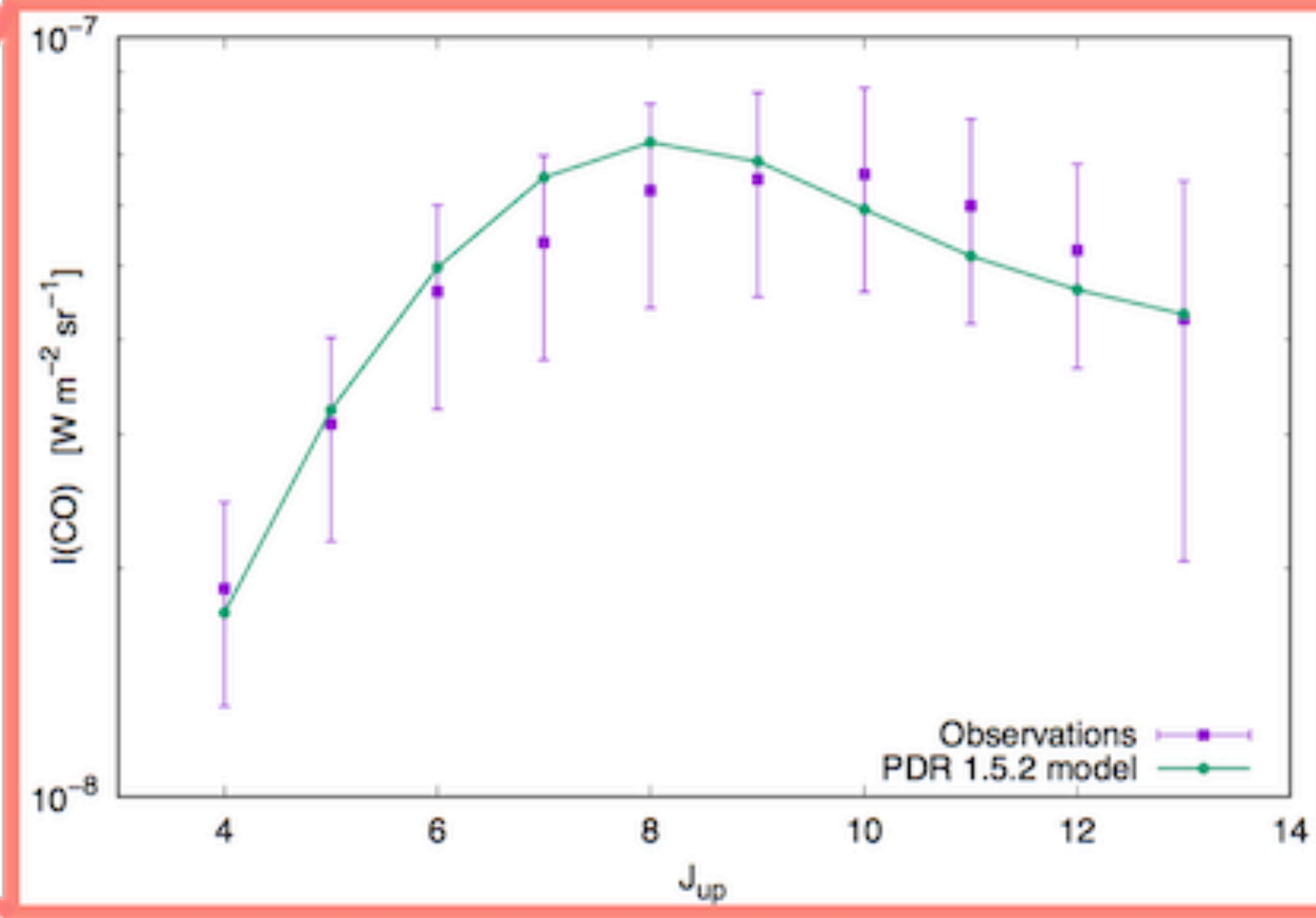


Carina nebula

(Wu et al., 2018)

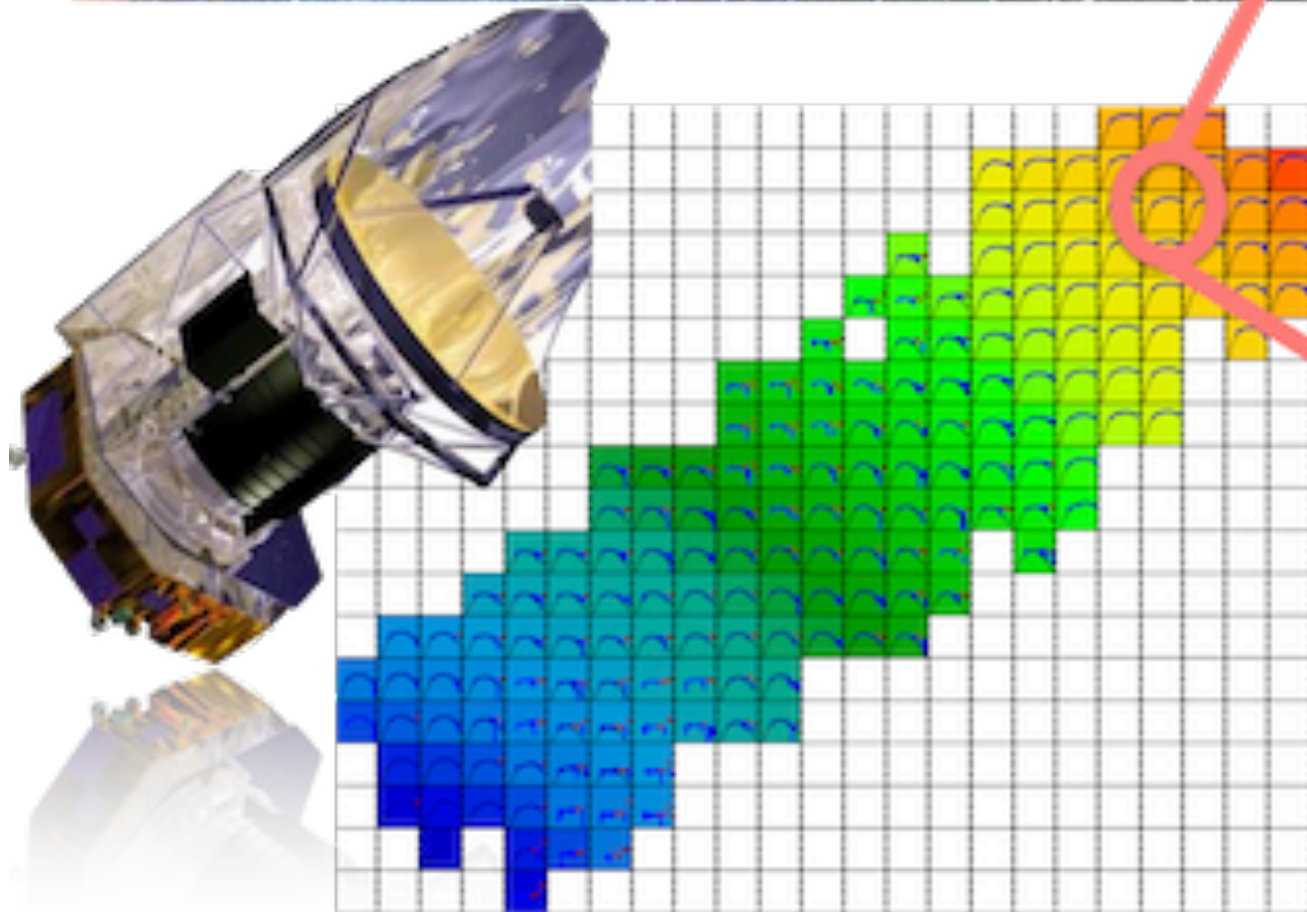
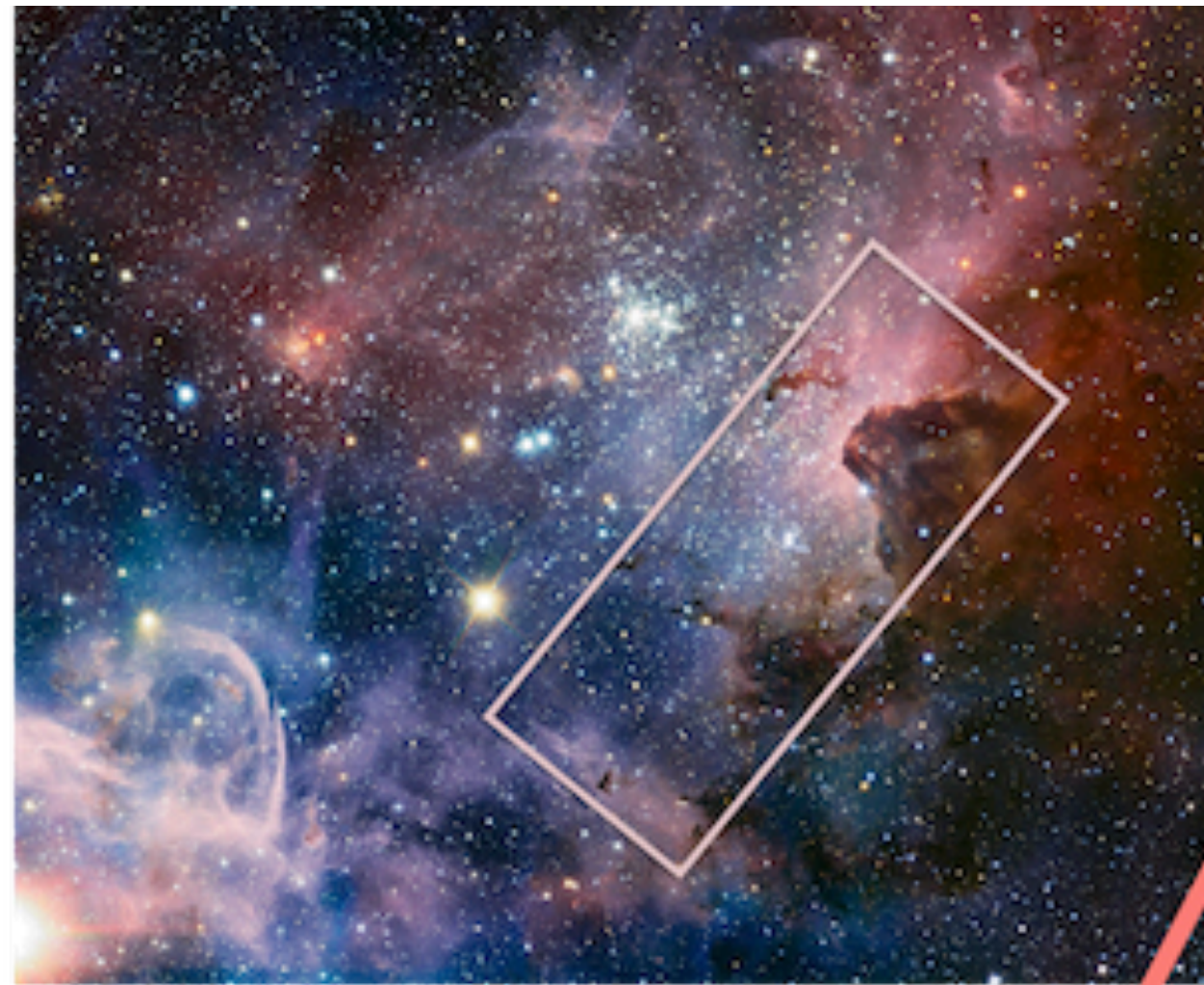


Pixel-wise estimation:
reconstructs well observations

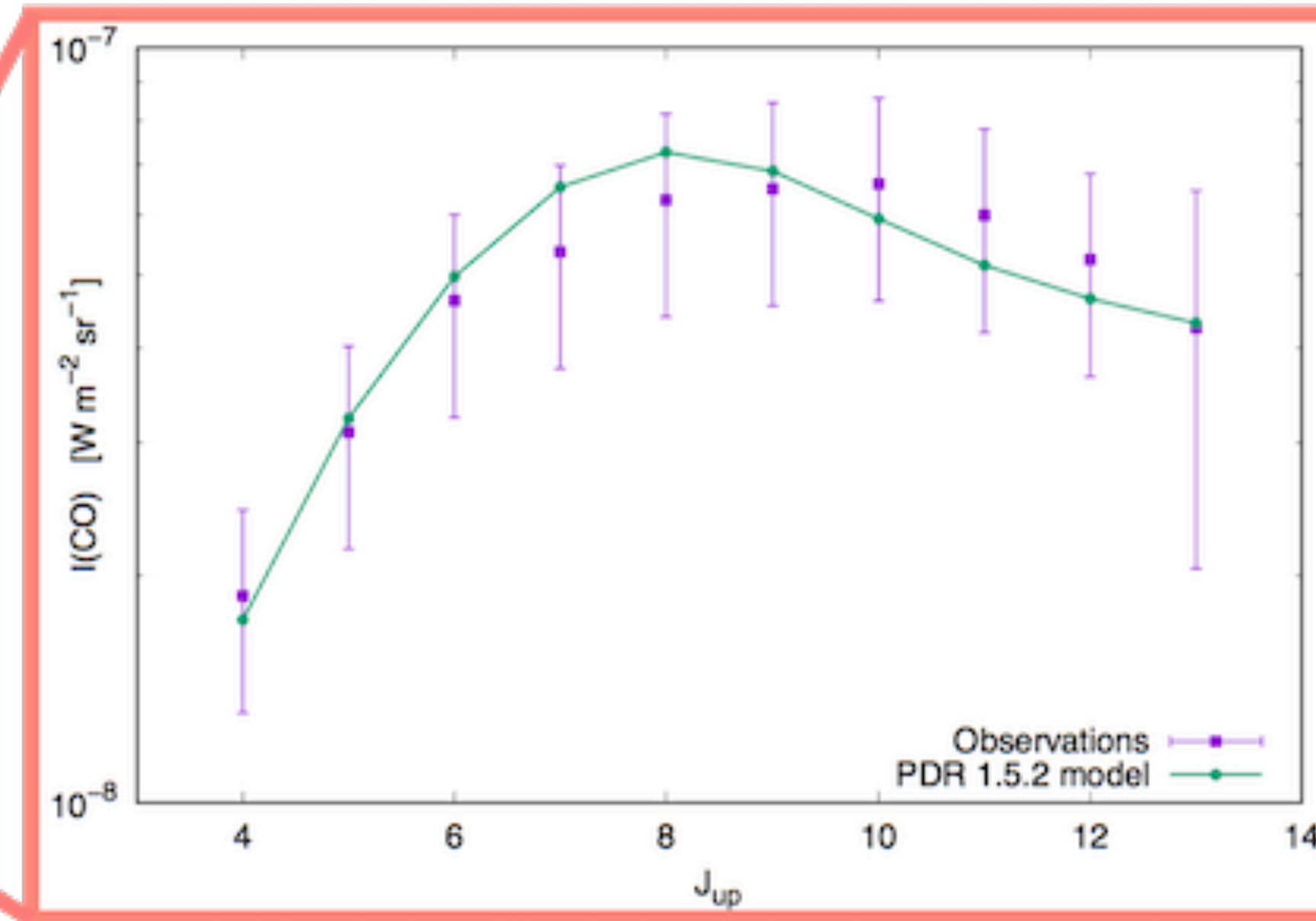


Carina nebula

(Wu et al., 2018)

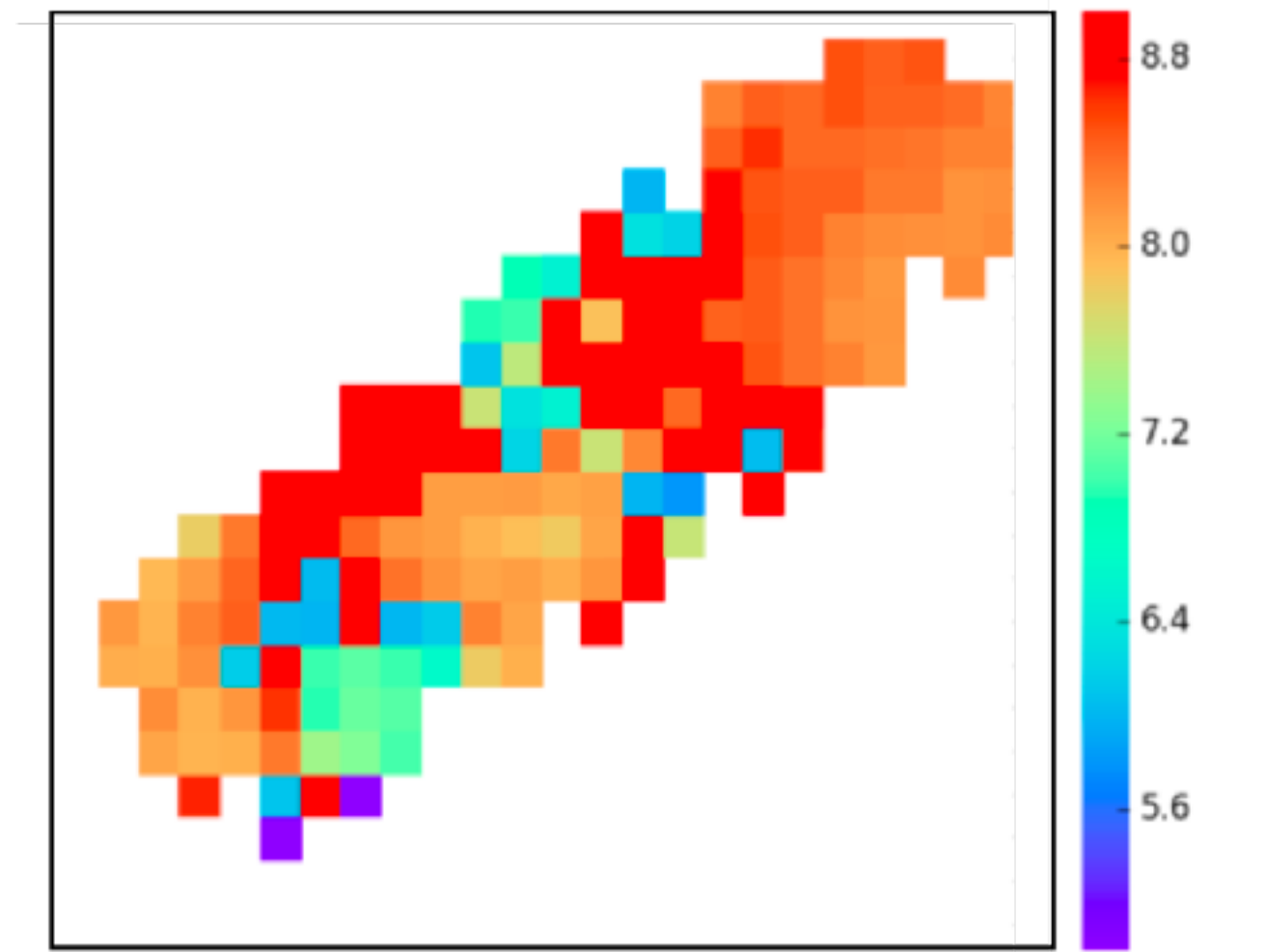


Pixel-wise estimation:
reconstructs well observations

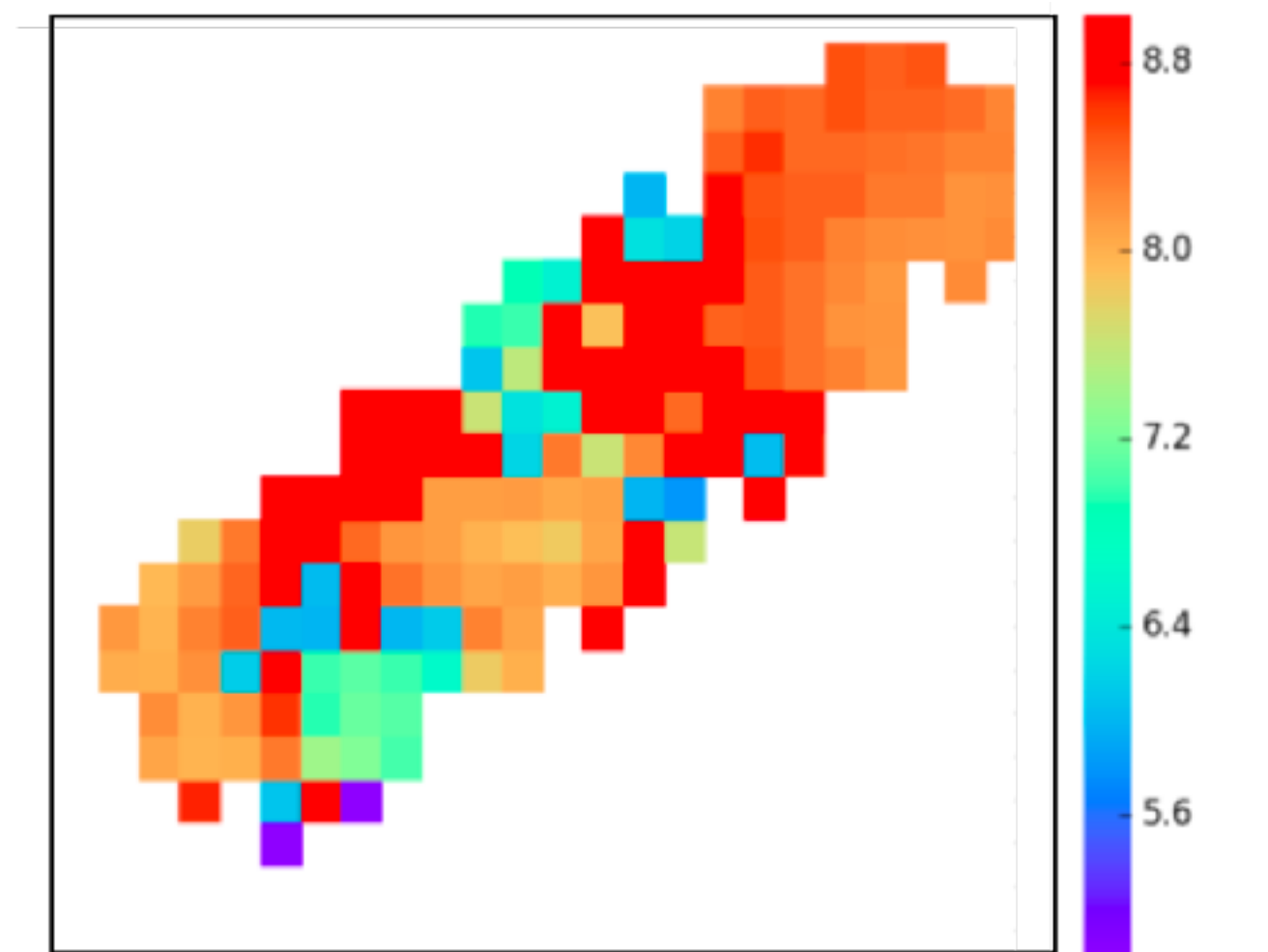


But reconstructed maps
have **no spatial coherence**
particularly in low SNR regions

$\log_{10} P_{th}$



$\log_{10} G_0$



Example: the OrionB cloud

Source: IRAM-30m, J.Pety, M. Guerin, consortium Orion-B

For better estimations:

- ⇒ Spatial regularization
- ⇒ uncertainty quantification
- ⇒ Fast

Method evaluated on a
synthetic PDR map

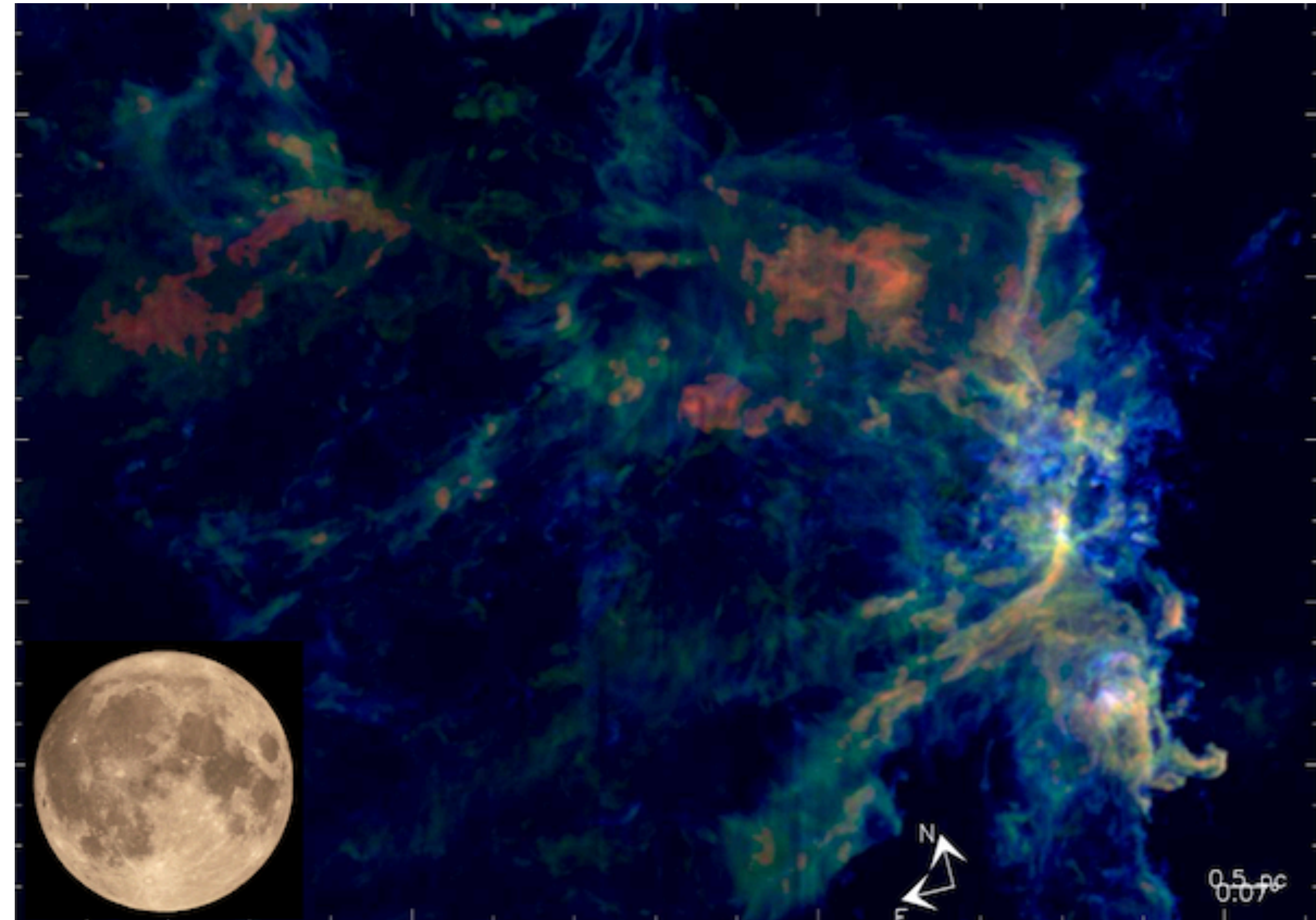
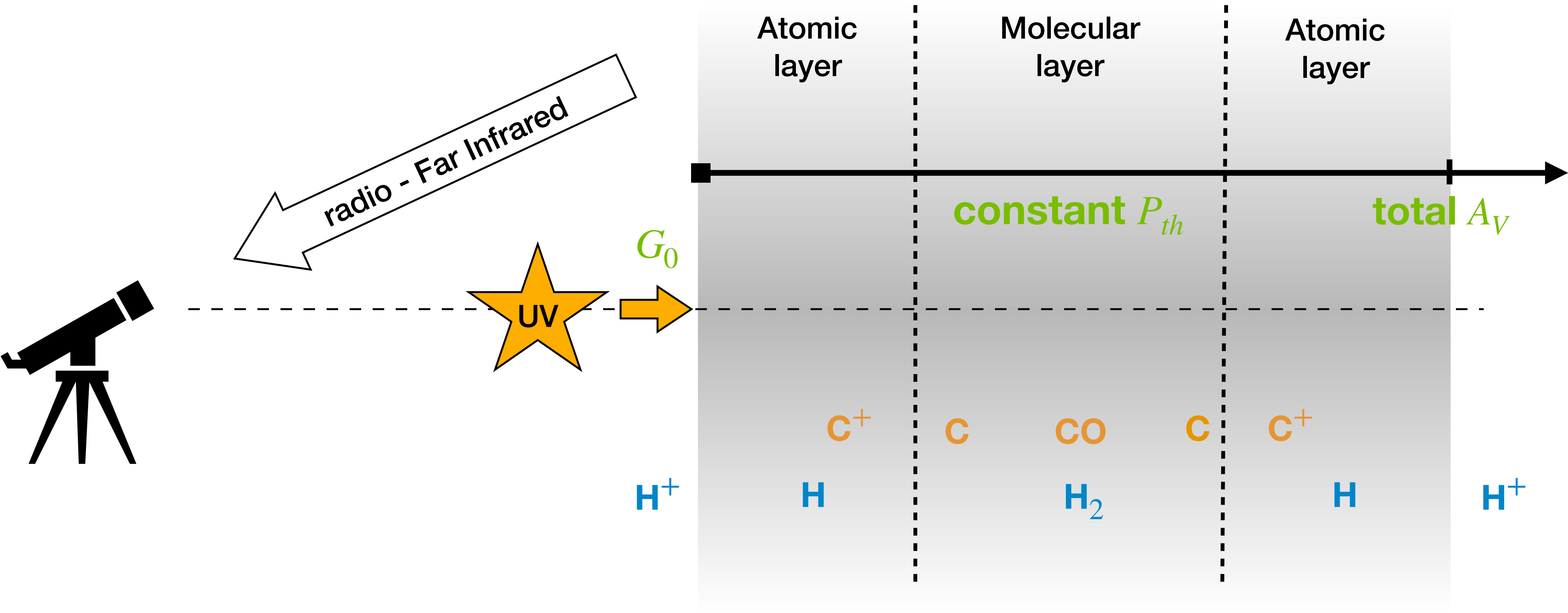


Photo-Dissociation Region (PDR)



Meudon PDR code

(Le Petit et al., 2006)

Parameters:

P_{th} - thermal pressure

G_0 - intensity of radiative field (in Habing units)

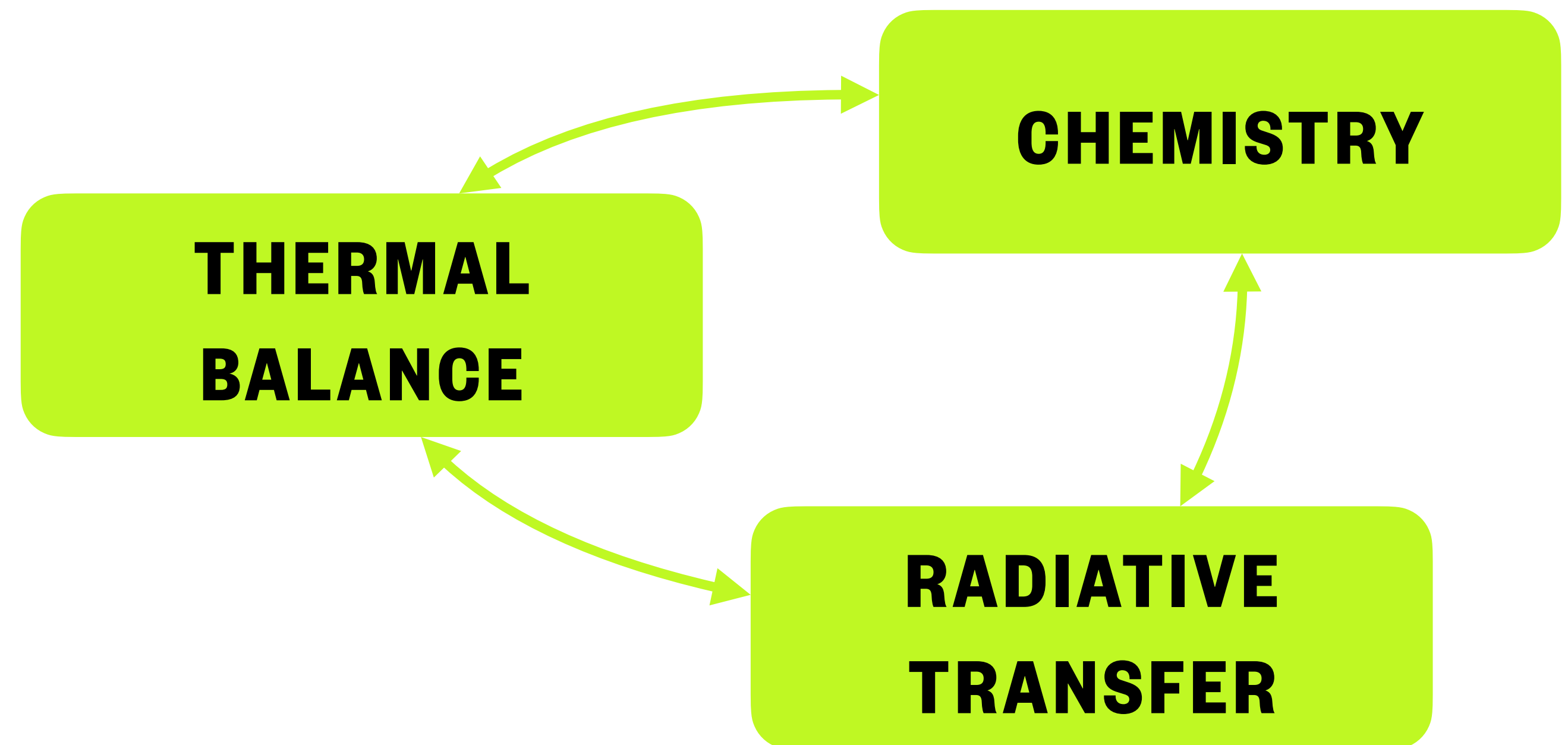
A_V - visual extinction

Code:

Iteratively Solves large set of partial differential equations

Observation:

Integrated intensities of a line



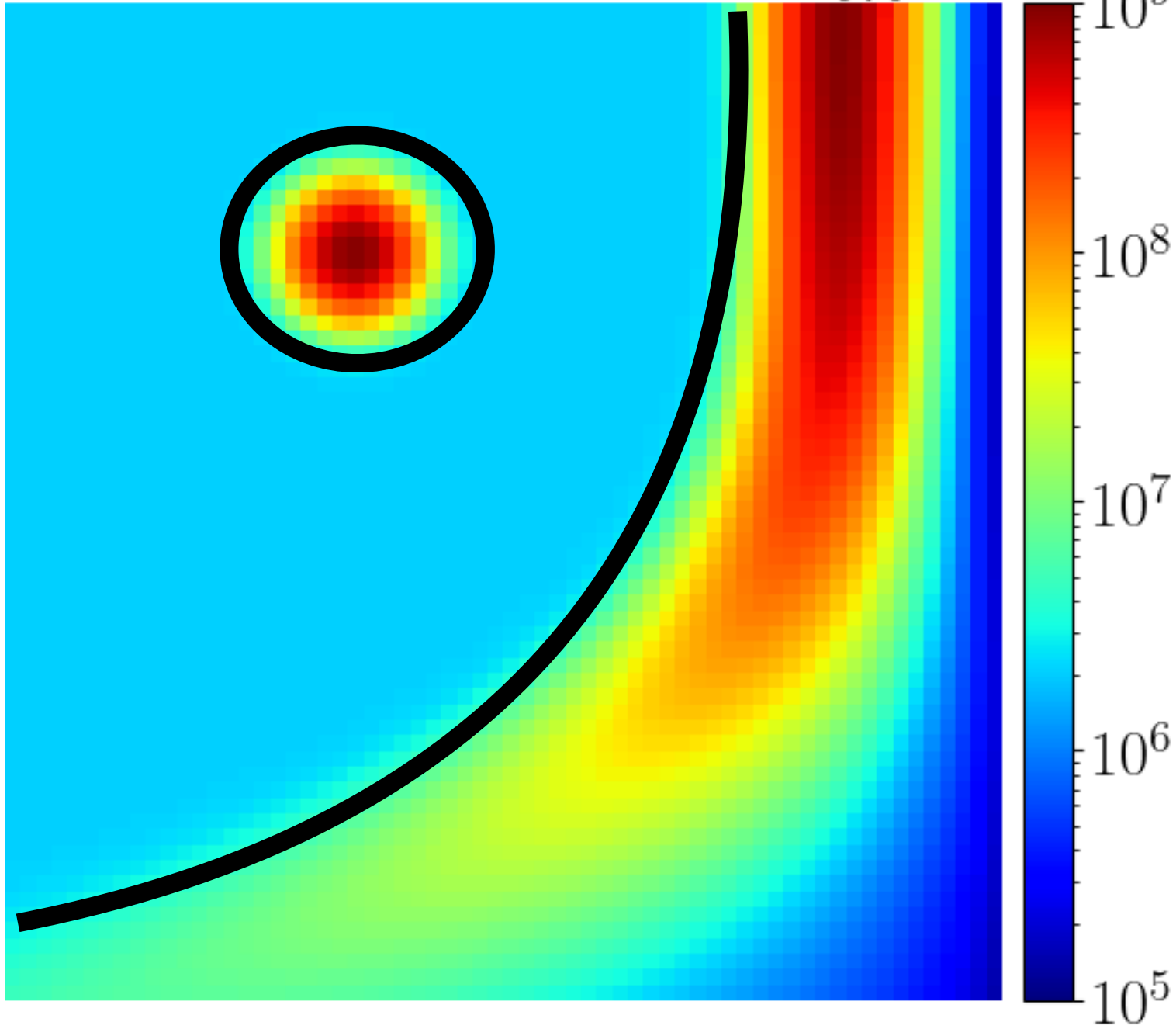
Synthetic PDR map

BURIED SOURCE

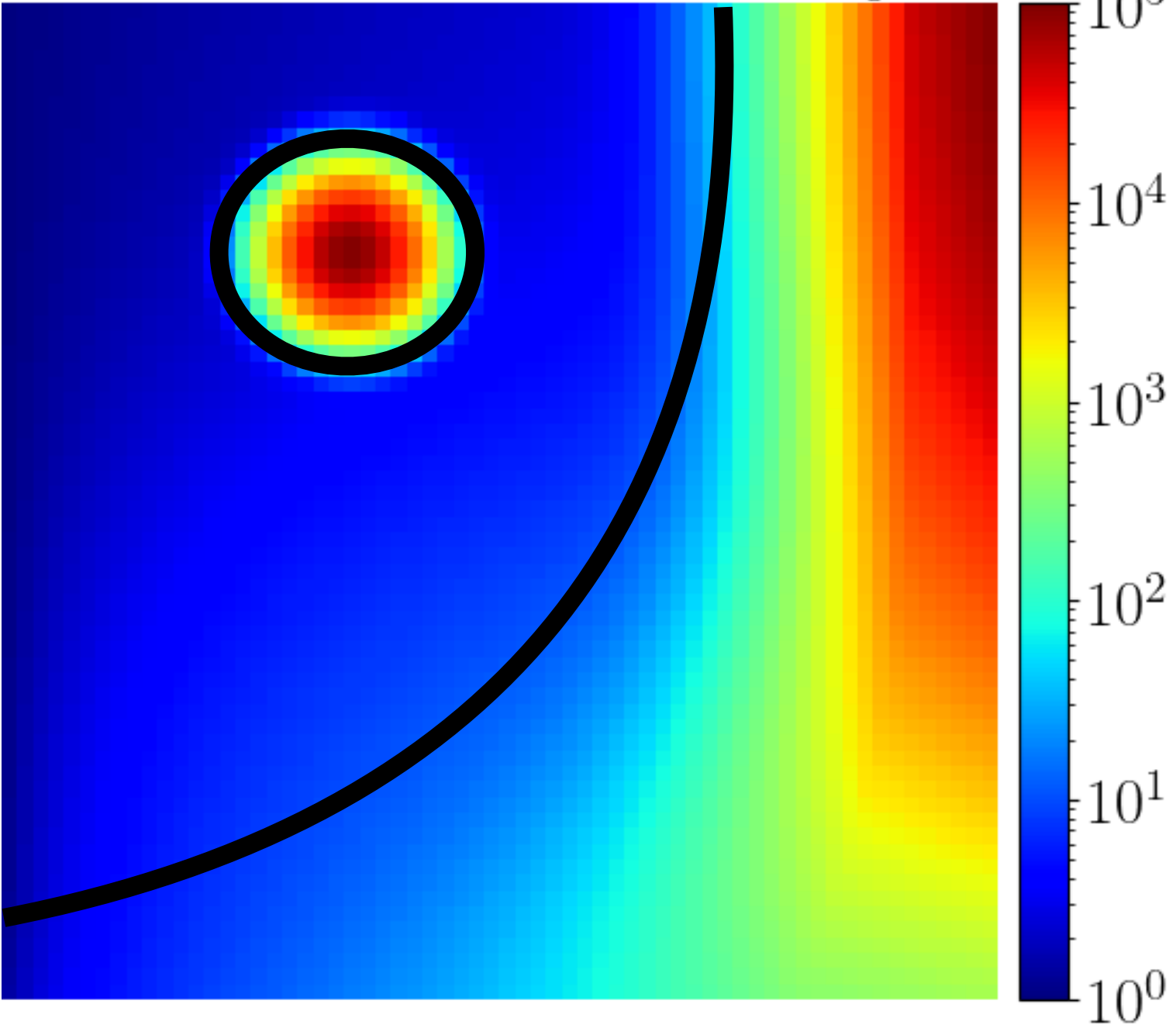
DARK CLOUD

PDR

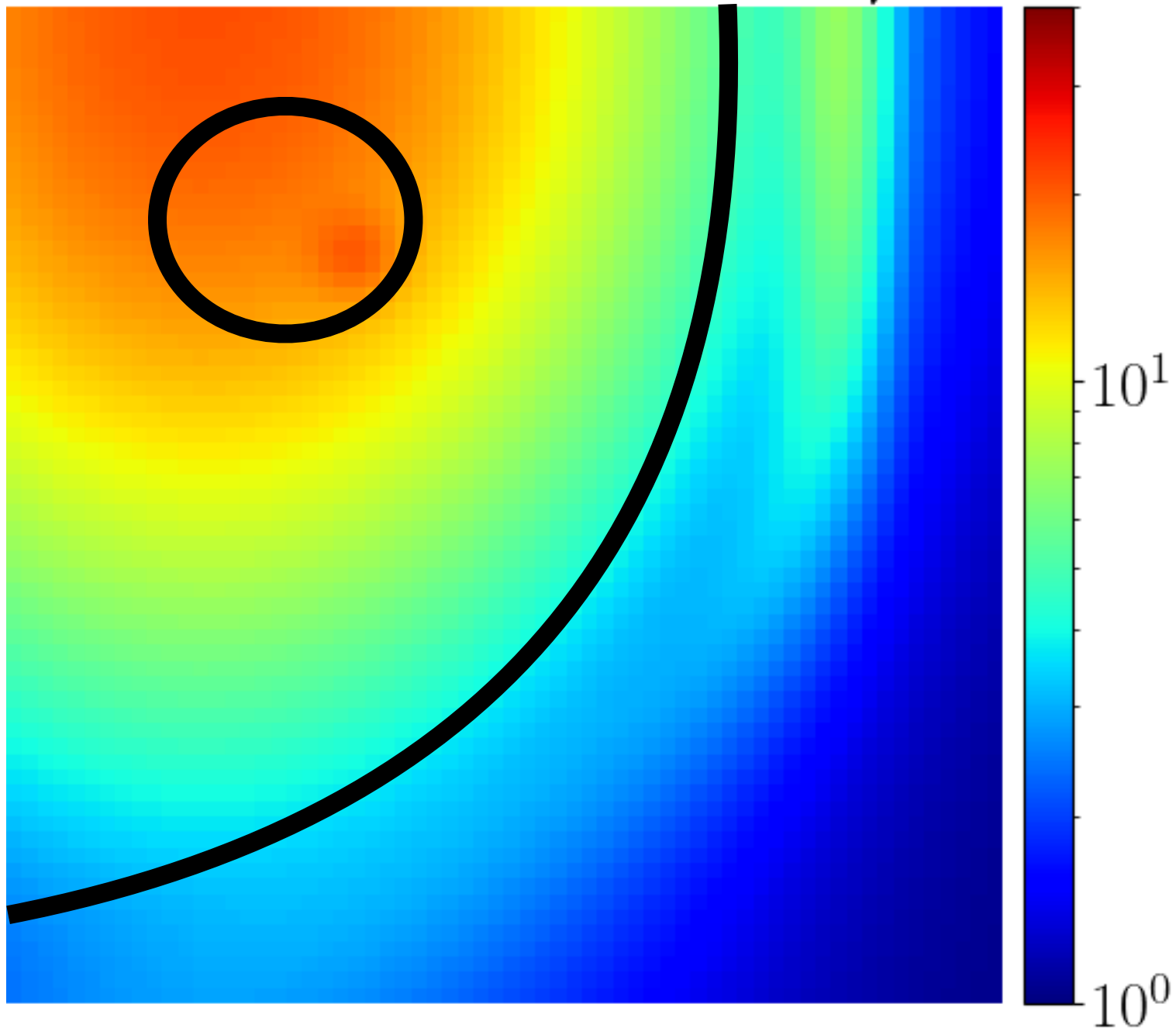
true values of P_{th}



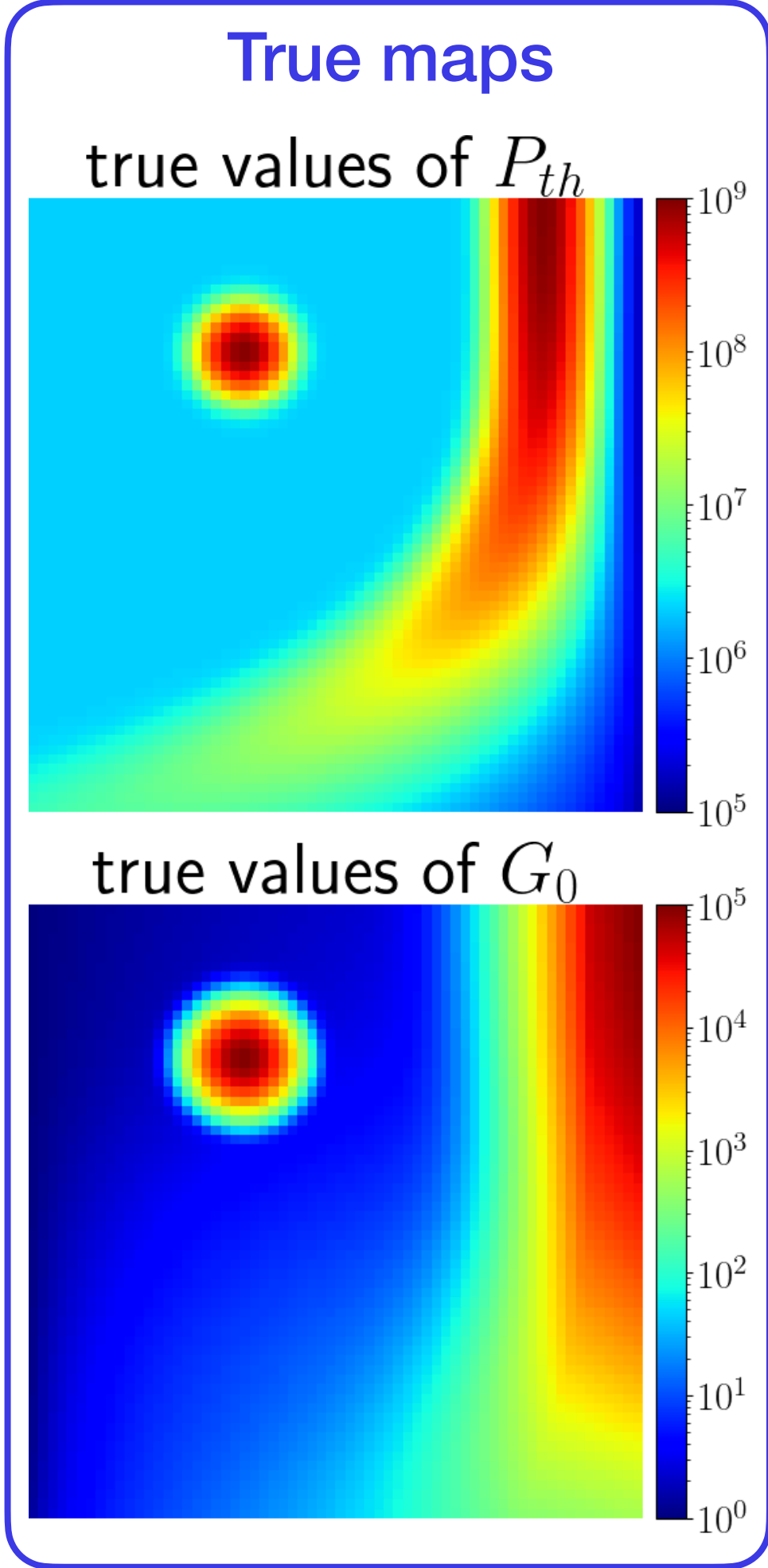
true values of G_0



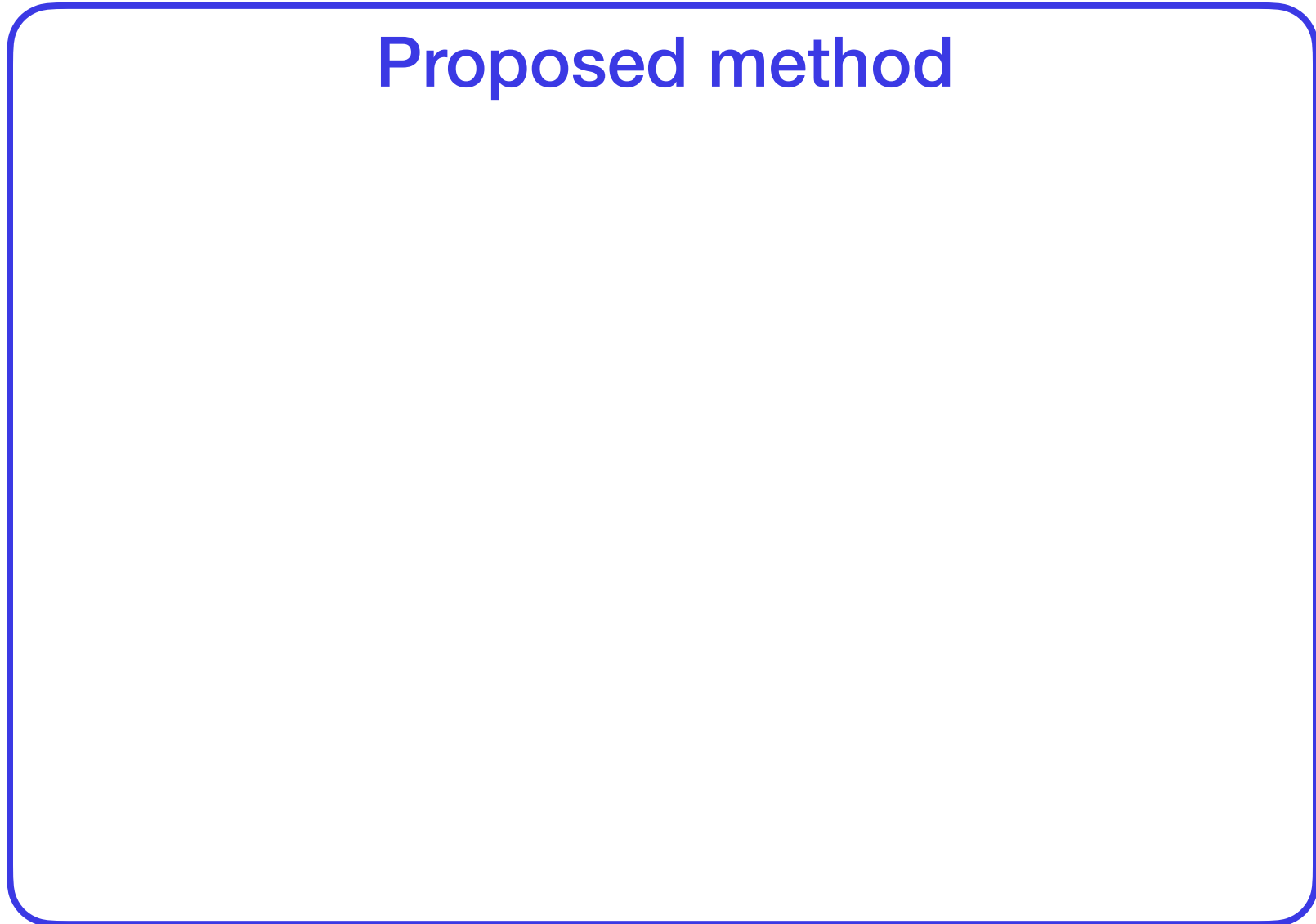
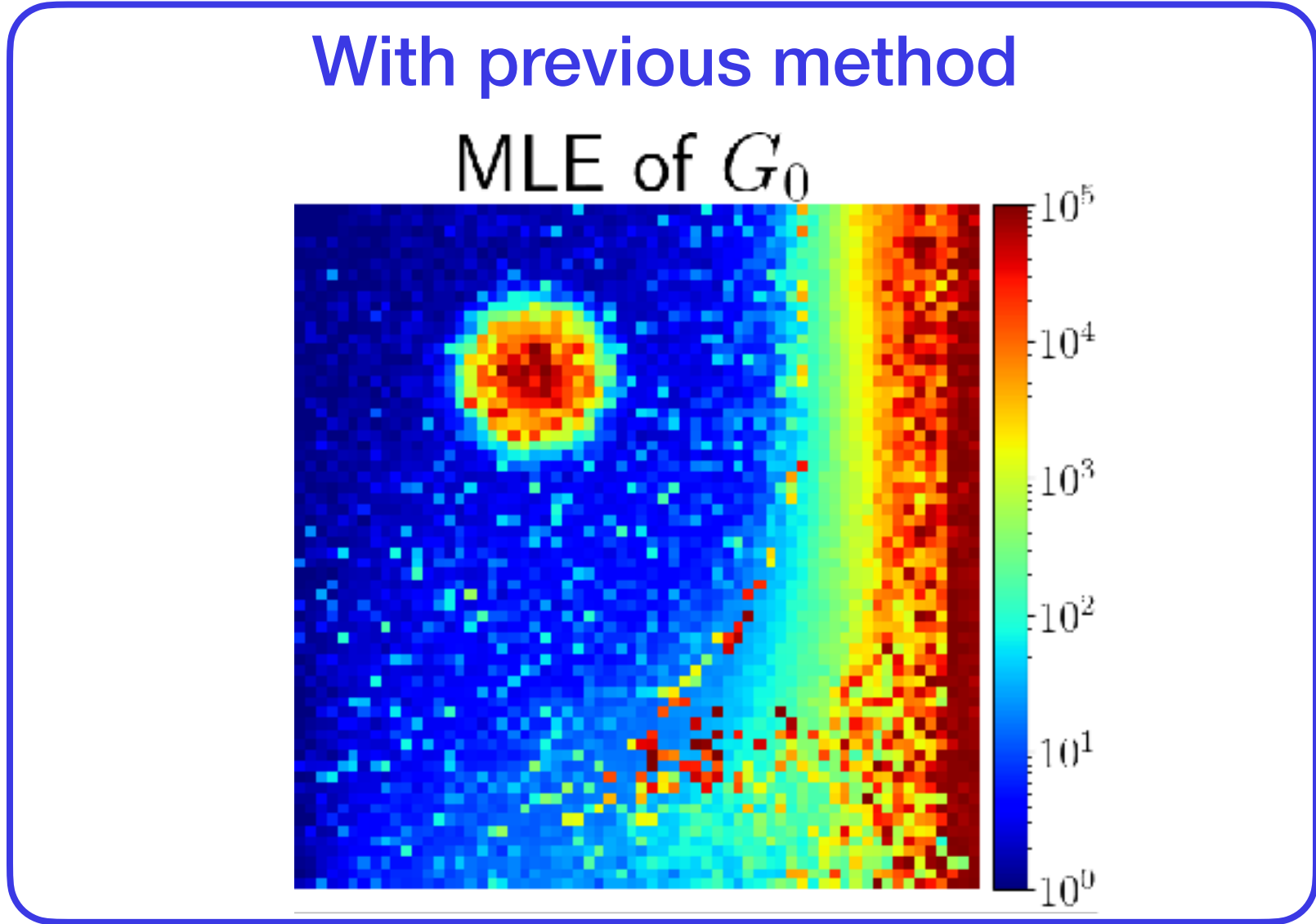
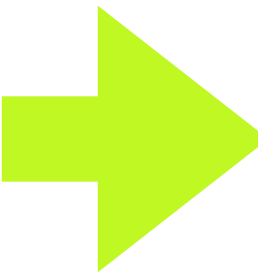
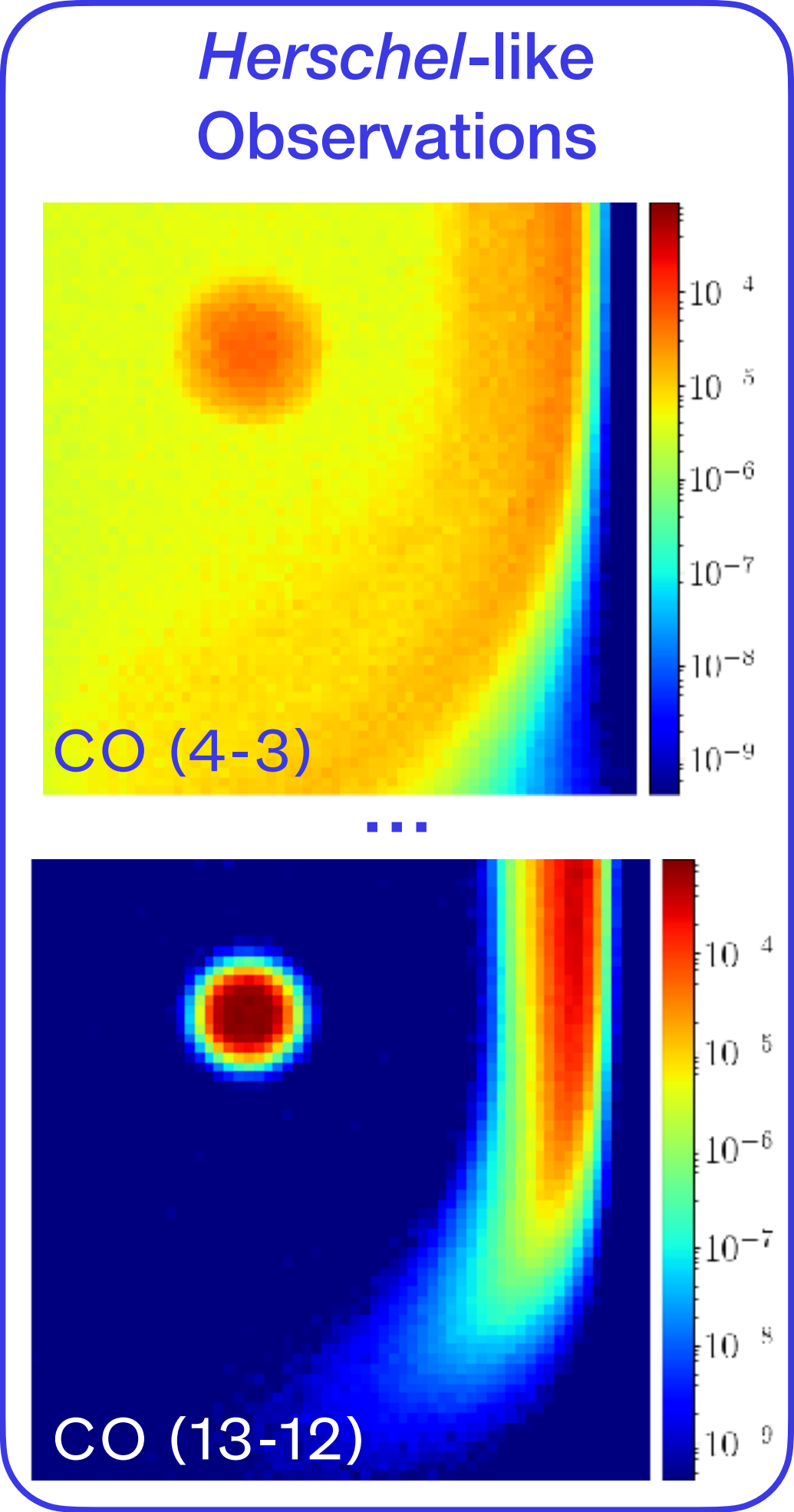
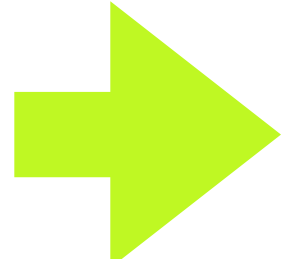
true values of A_V



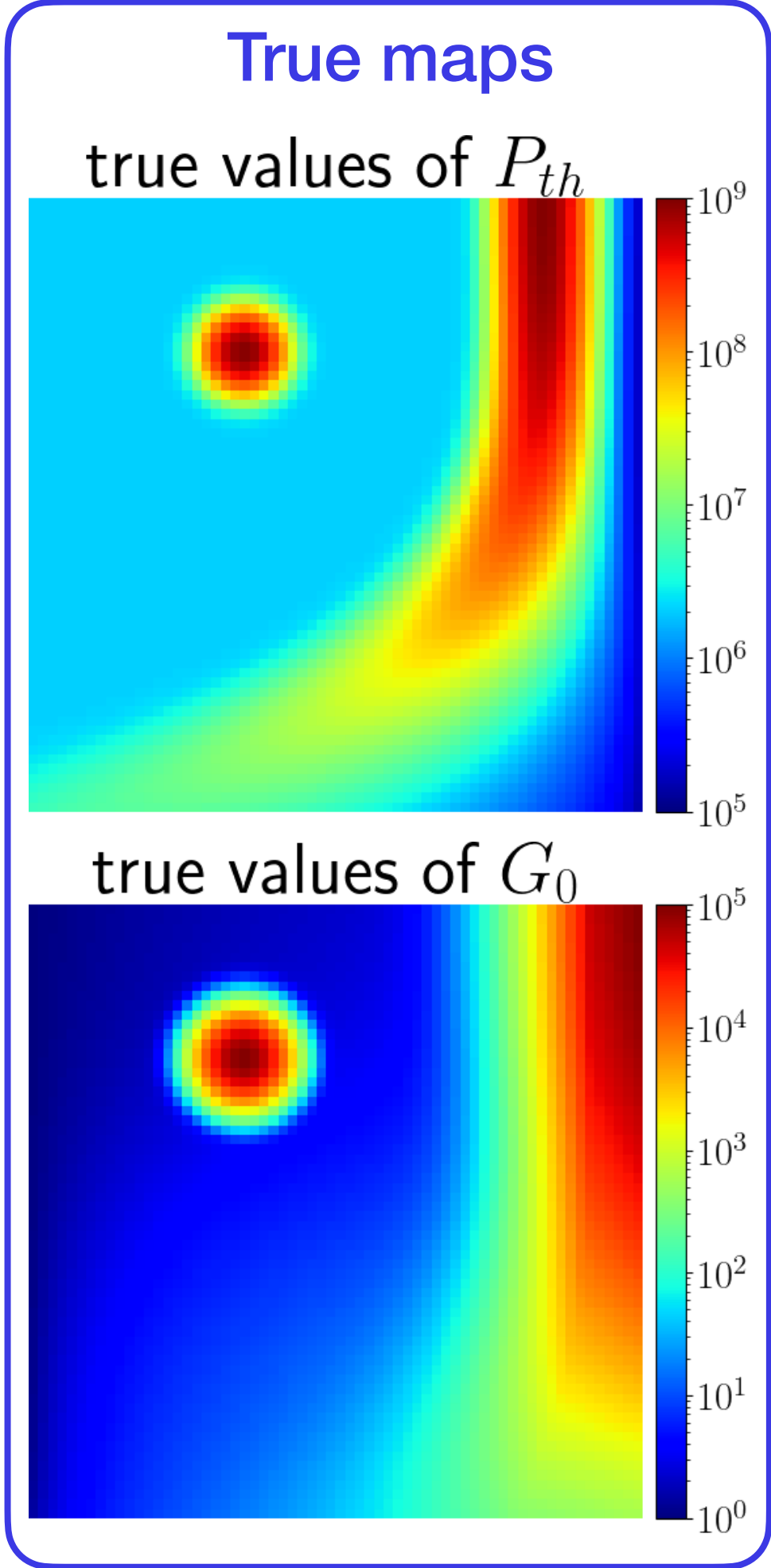
Synthetic PDR map



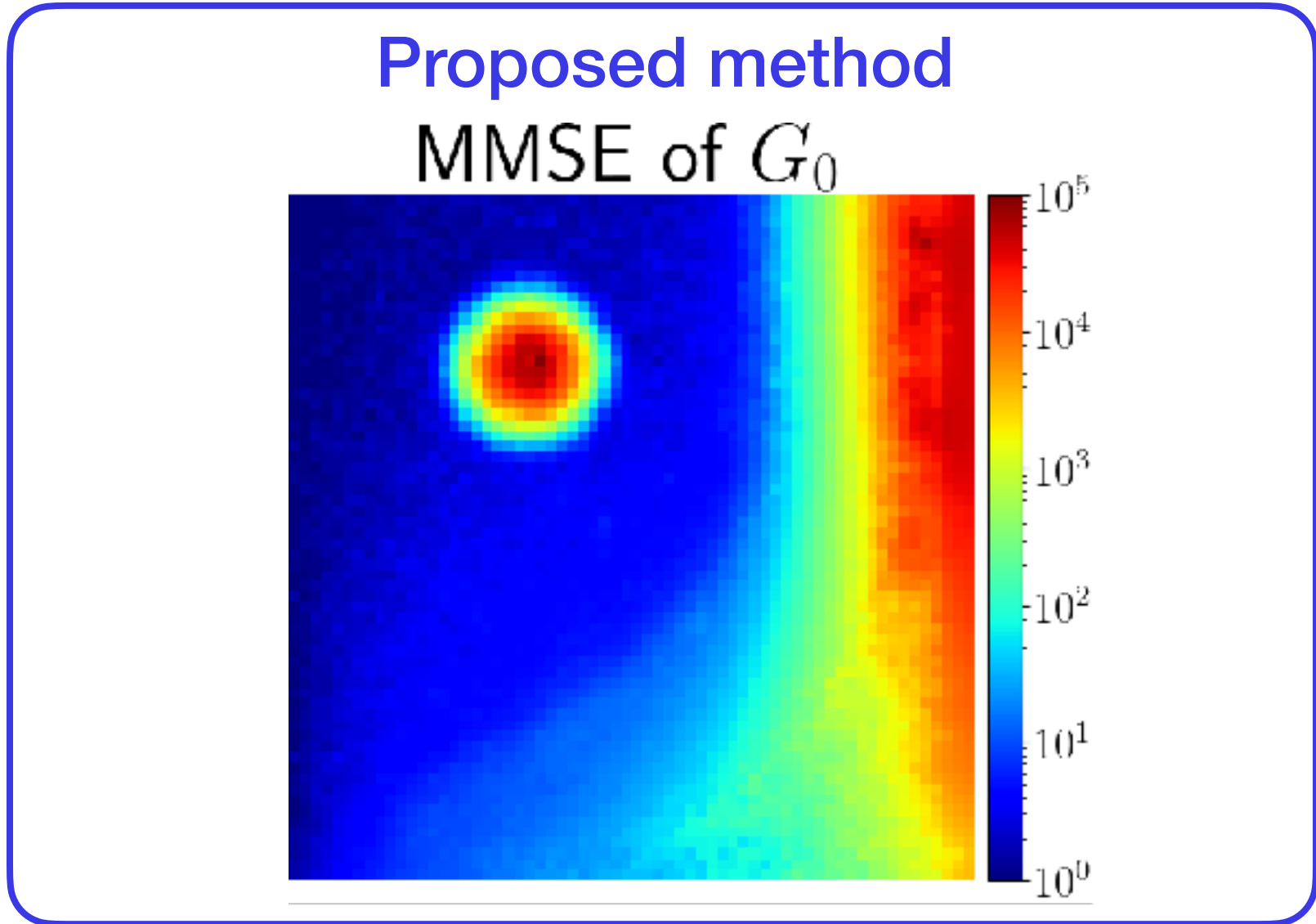
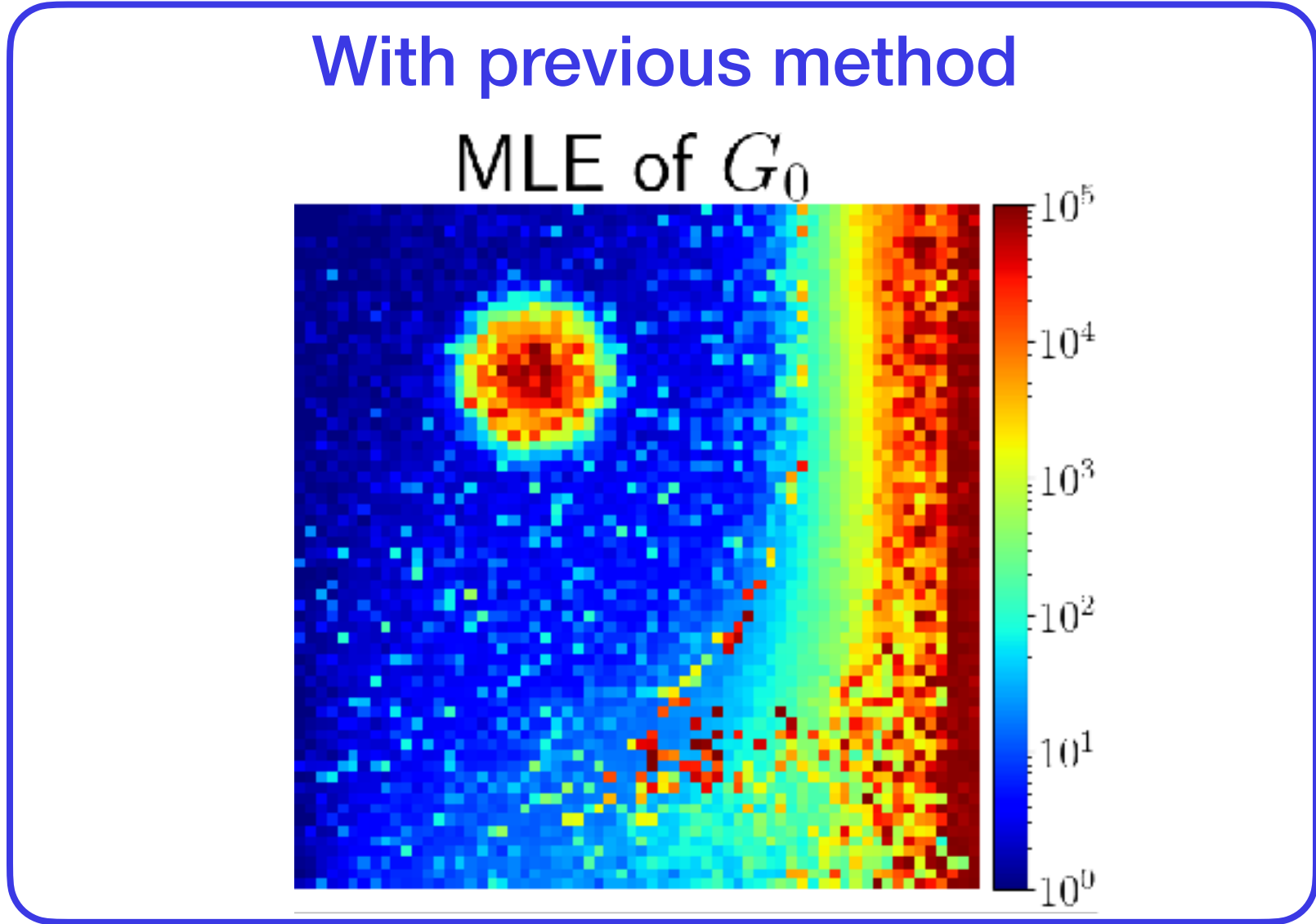
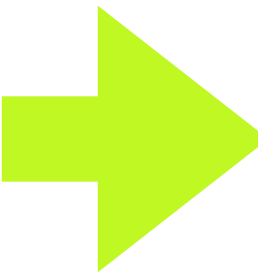
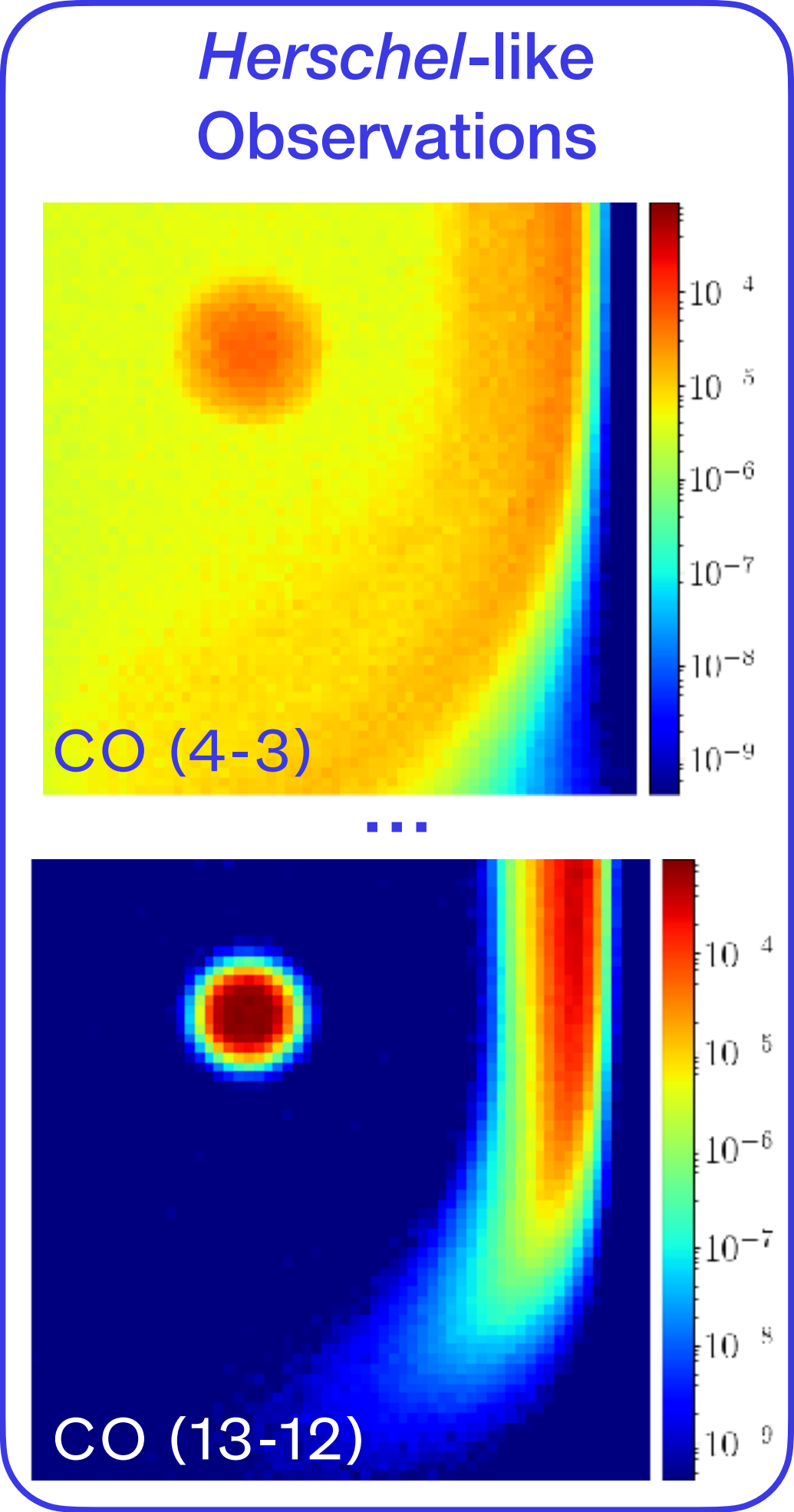
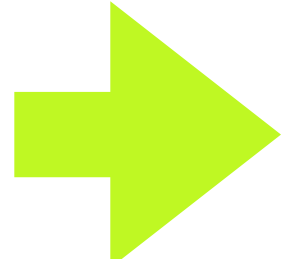
Meudon PDR
+
Noise



Synthetic PDR map



Meudon PDR
+
Noise



Bayesian approach

Inference with **credibility intervals**
More complete description of parameter space



A posteriori probability distribution $\mathbb{P}[(P_{th}, G_0, A_V) | Y]$

$$\underbrace{\mathbb{P}[(P_{th}, G_0, A_V) | Y]}_{\text{A posteriori}} \propto \underbrace{\mathbb{P}[Y | (P_{th}, G_0, A_V)]}_{\text{Likelihood}} \underbrace{\mathbb{P}[(P_{th}, G_0, A_V)]}_{\text{Spatial prior}}$$

Complex distribution
⇒ impossible to extract estimators as is
⇒ sample from it with **MCMC algorithm**

Observation model

$$\left\{ \begin{array}{l} \text{If detected: } y_{n,\ell} = \epsilon_{n,\ell}^{(m)} f_{\ell}(\theta_n) + \epsilon_{n,\ell}^{(a)} \\ \text{Otherwise: } y_{n,\ell} \leq \omega \end{array} \right\}$$

With

$y_{n,\ell}$: actual observation

$f_{\ell}(\theta_n)$: predicted observation

$\epsilon_{n,\ell}^{(m)}$: multiplicative noise

$\epsilon_{n,\ell}^{(a)}$: additive noise

ω : telescope detectability limit

How to deal with **expensive numerical code** f ?

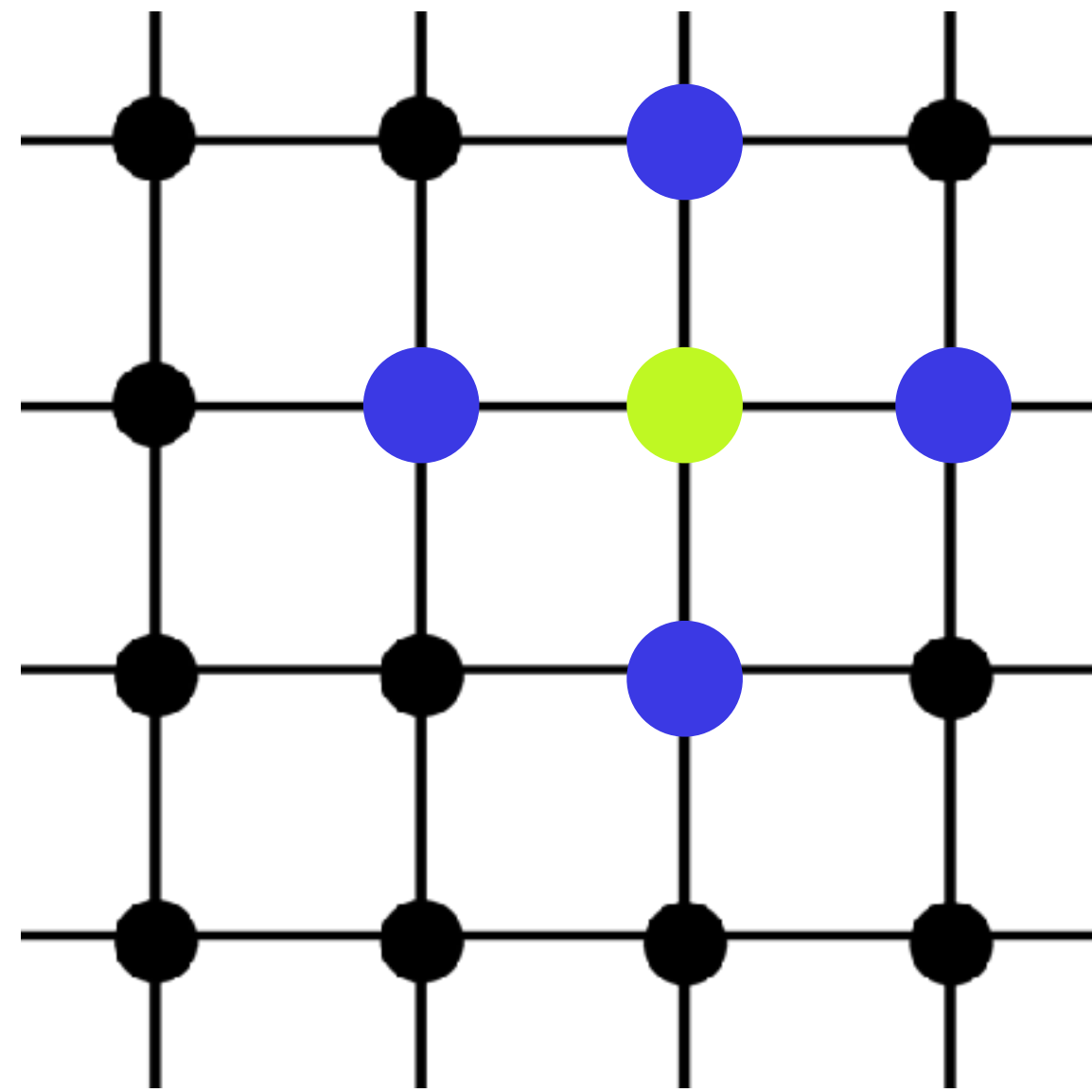
Approximation of f
(e.g., with a neural network)

How to deal with **both** additive and multiplicative noises ?

Approximation of likelihood

SNR	Noise model
Low	Additive
High	Multiplicative
Intermediate	Mixture

Spatial Regularization

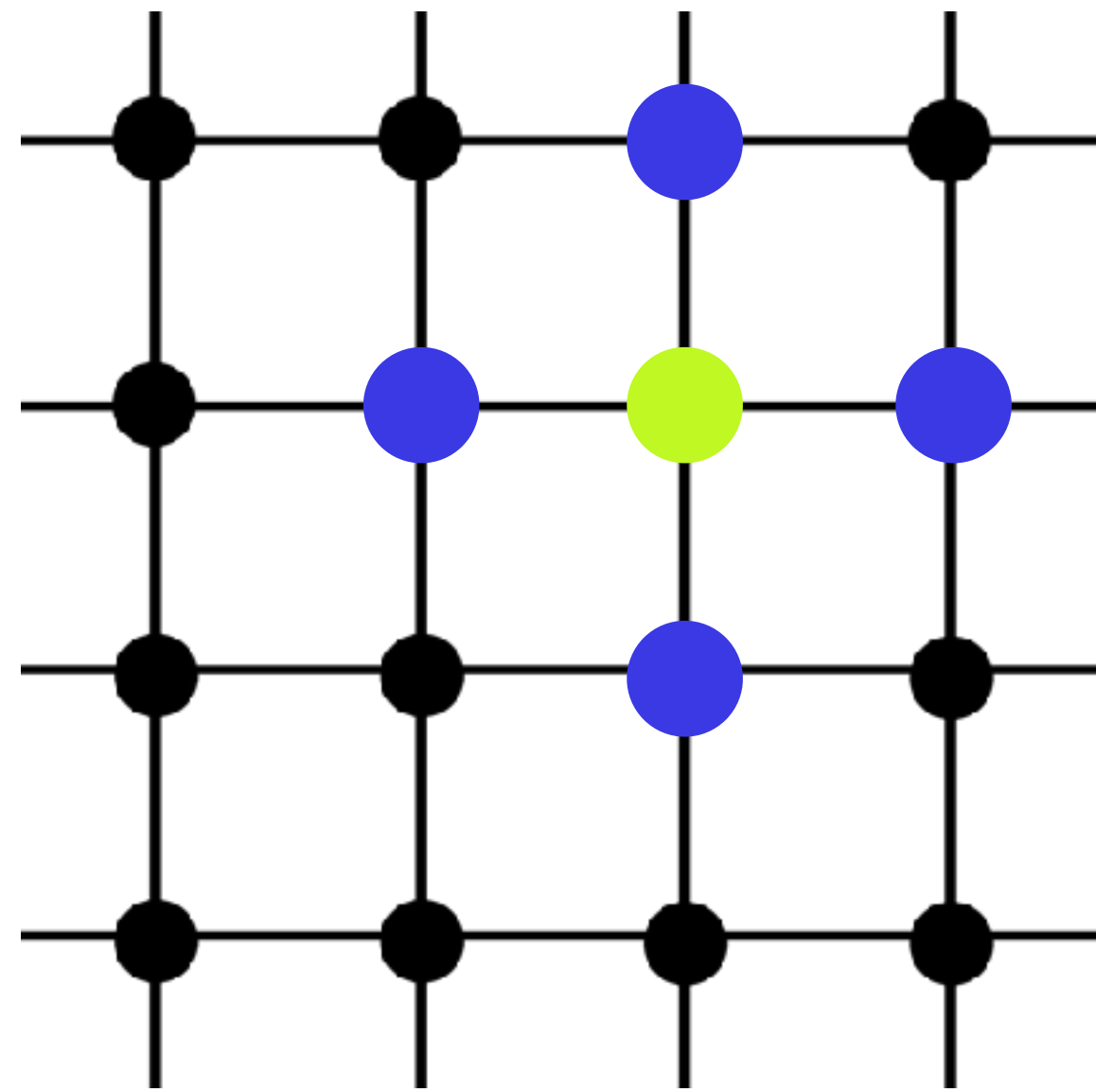


● Neighbour of ●

● Should be close to the average of ●

≈ **adaptive stacking**

Spatial Regularization

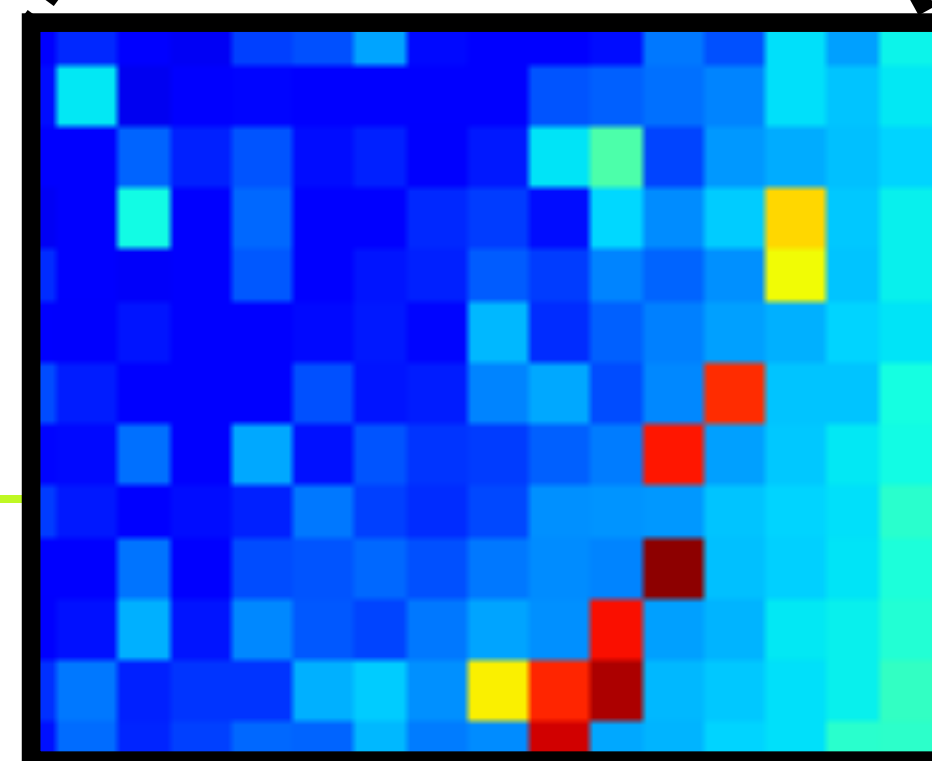
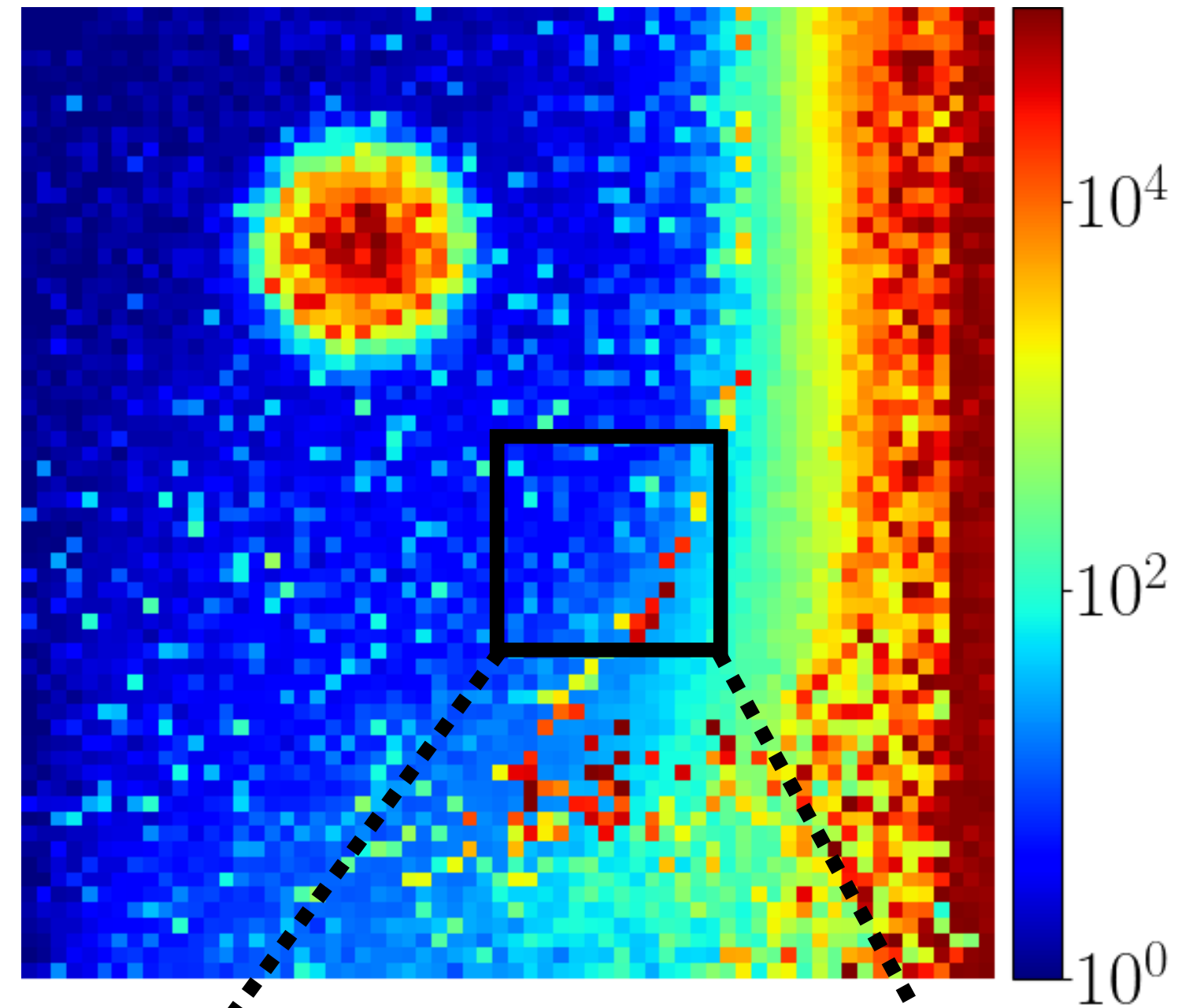


● Neighbour of ●

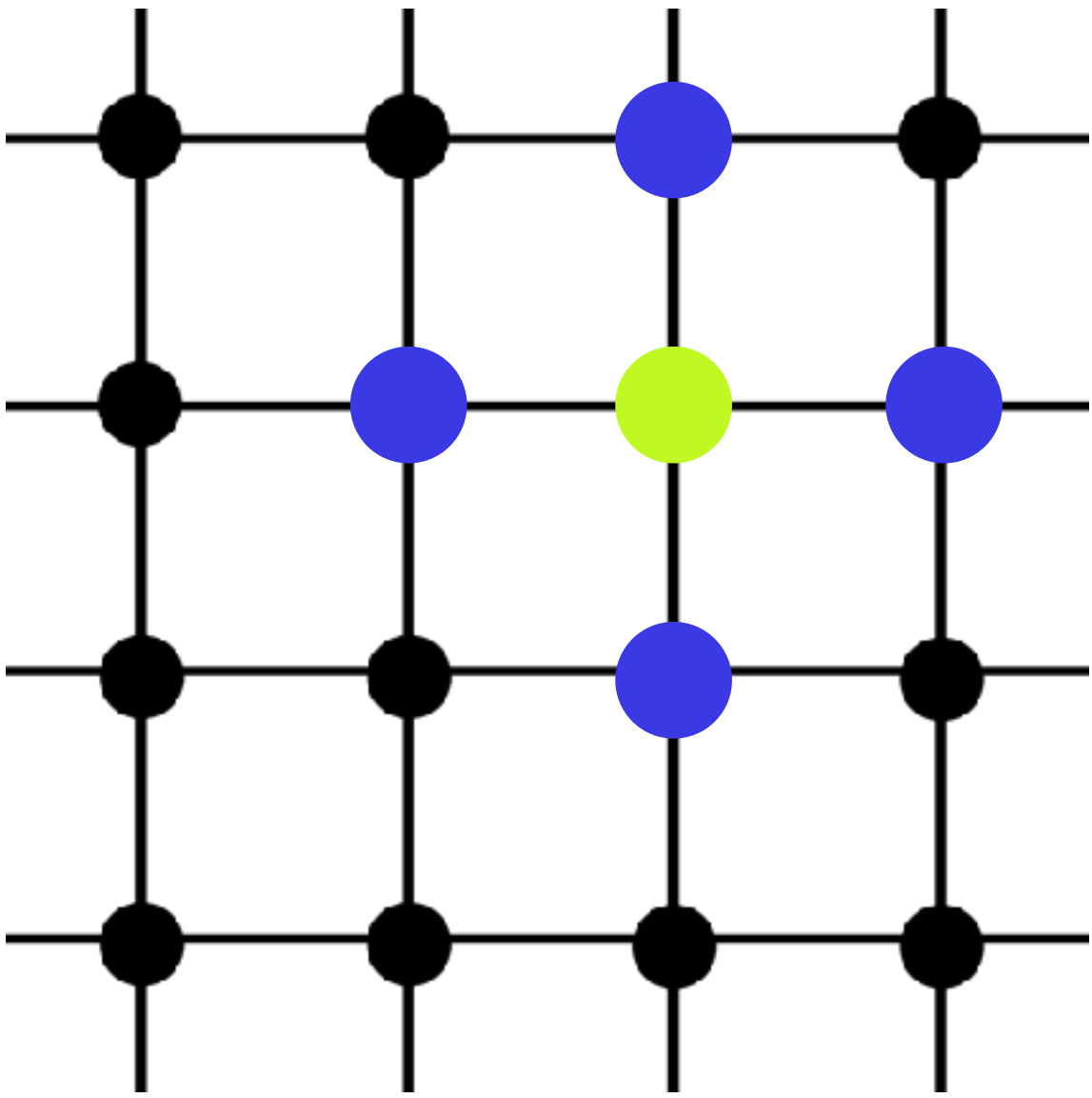
● Should be close to the average of ●

≈ **adaptive stacking**

Not smooth \implies High penalty ✖



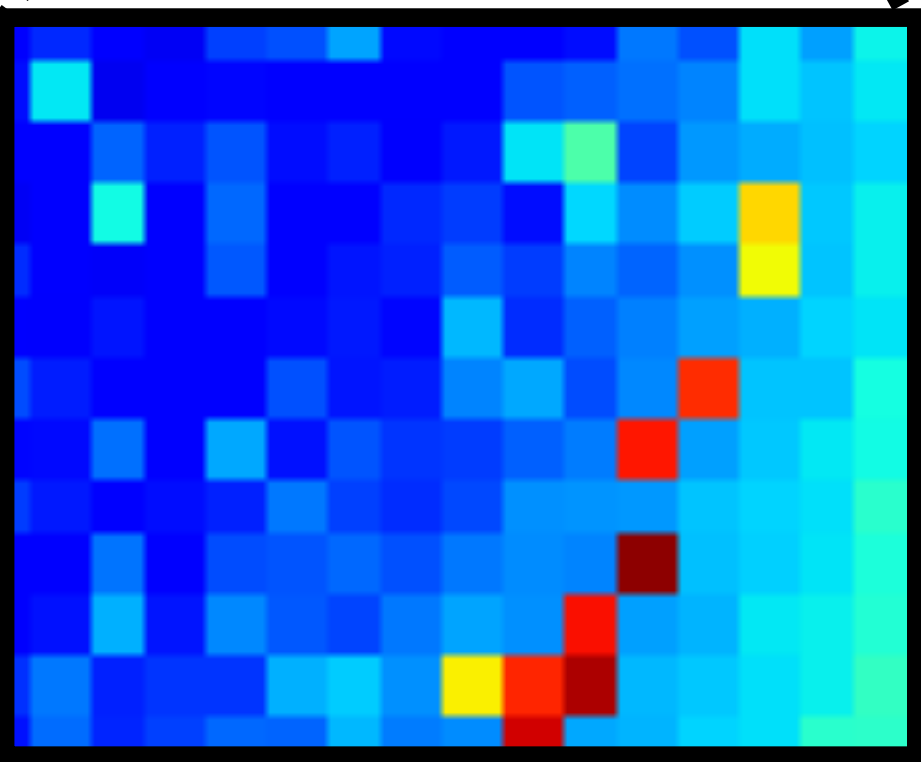
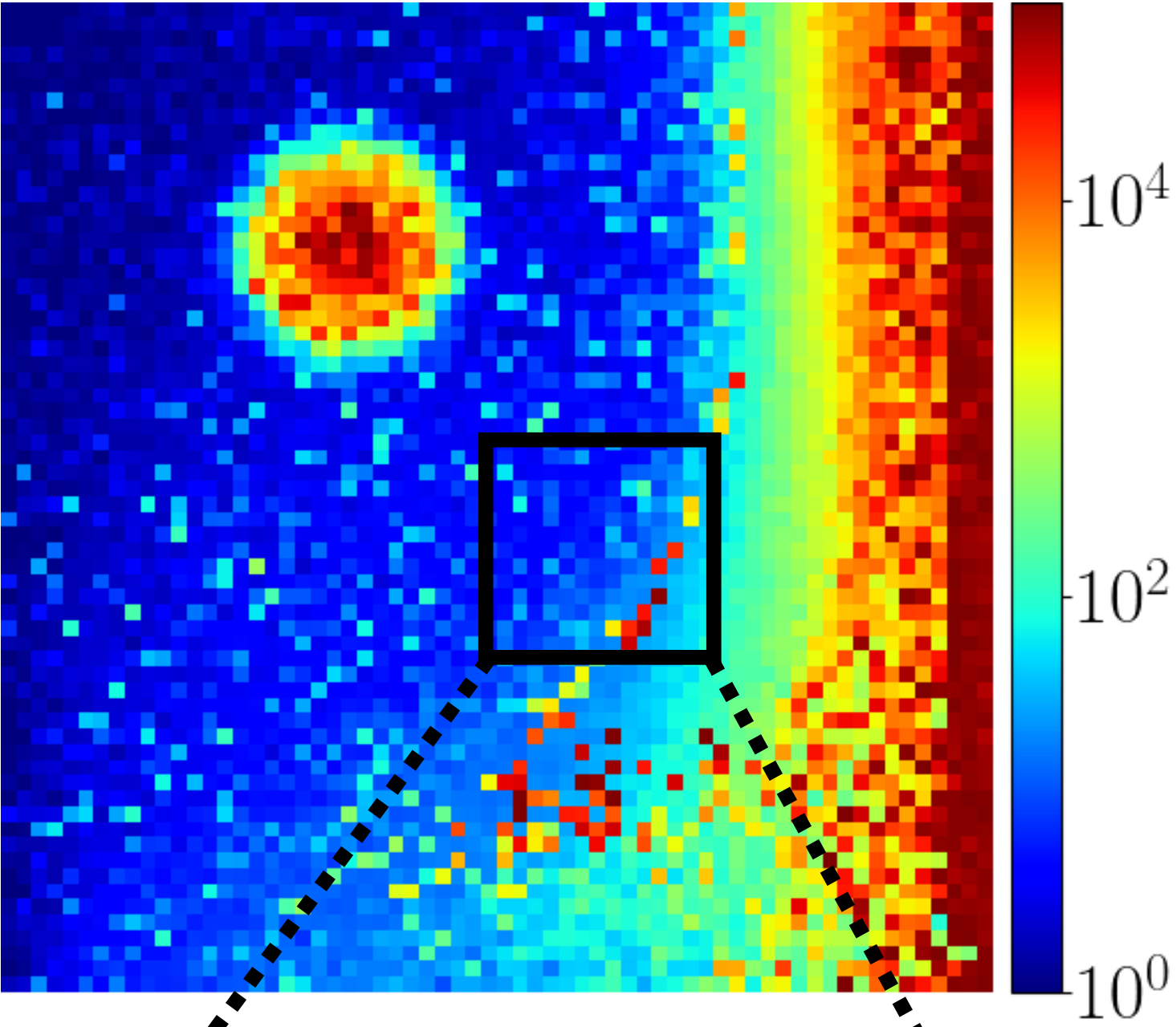
Spatial Regularization



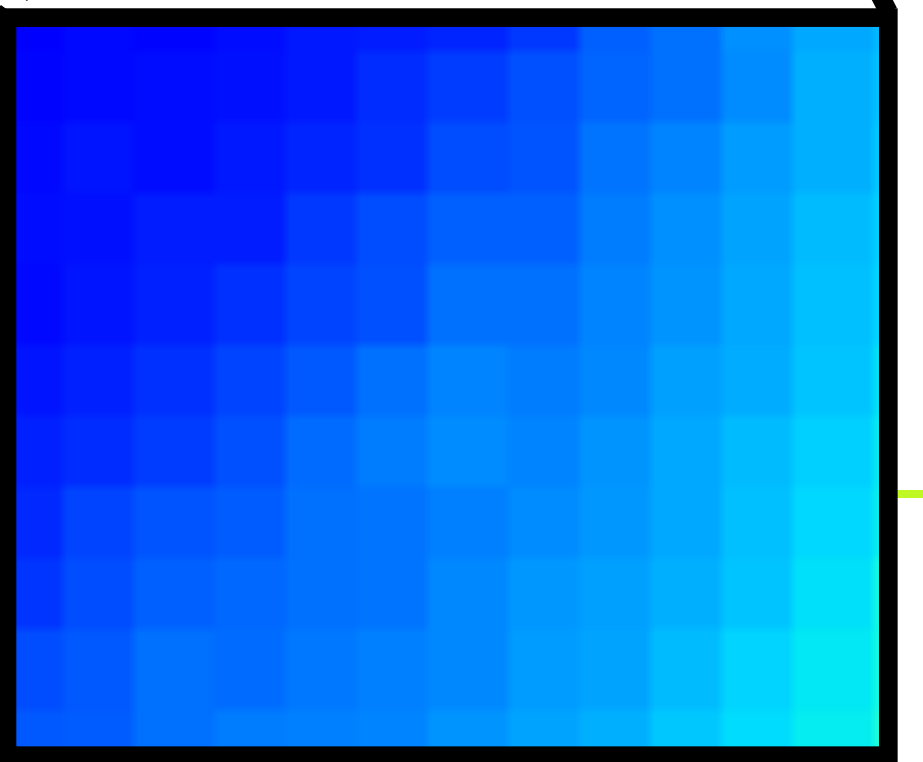
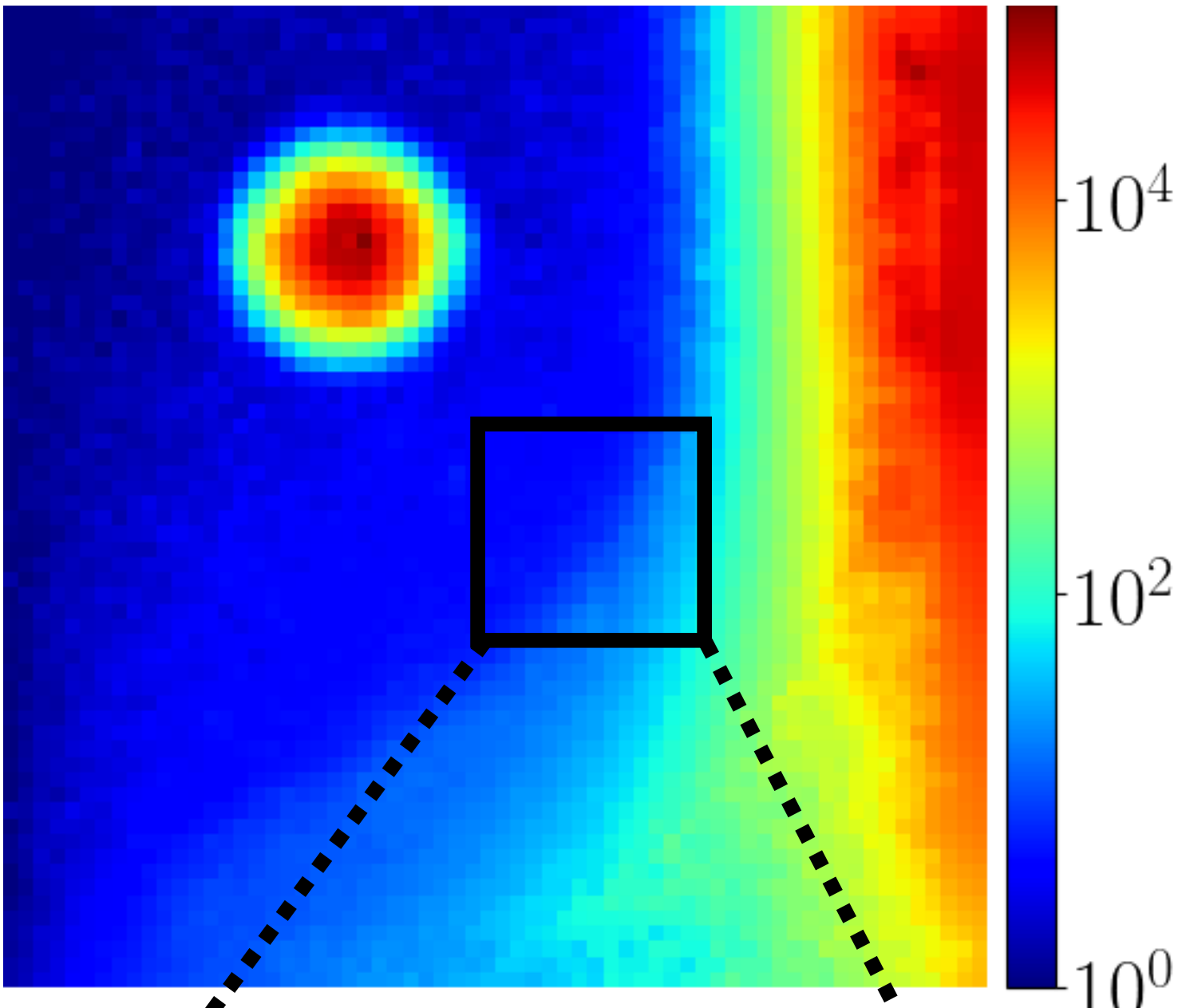
● Neighbour of ●
● Should be close to the average of ●

≈ **adaptive stacking**

Not smooth \implies High penalty ✗

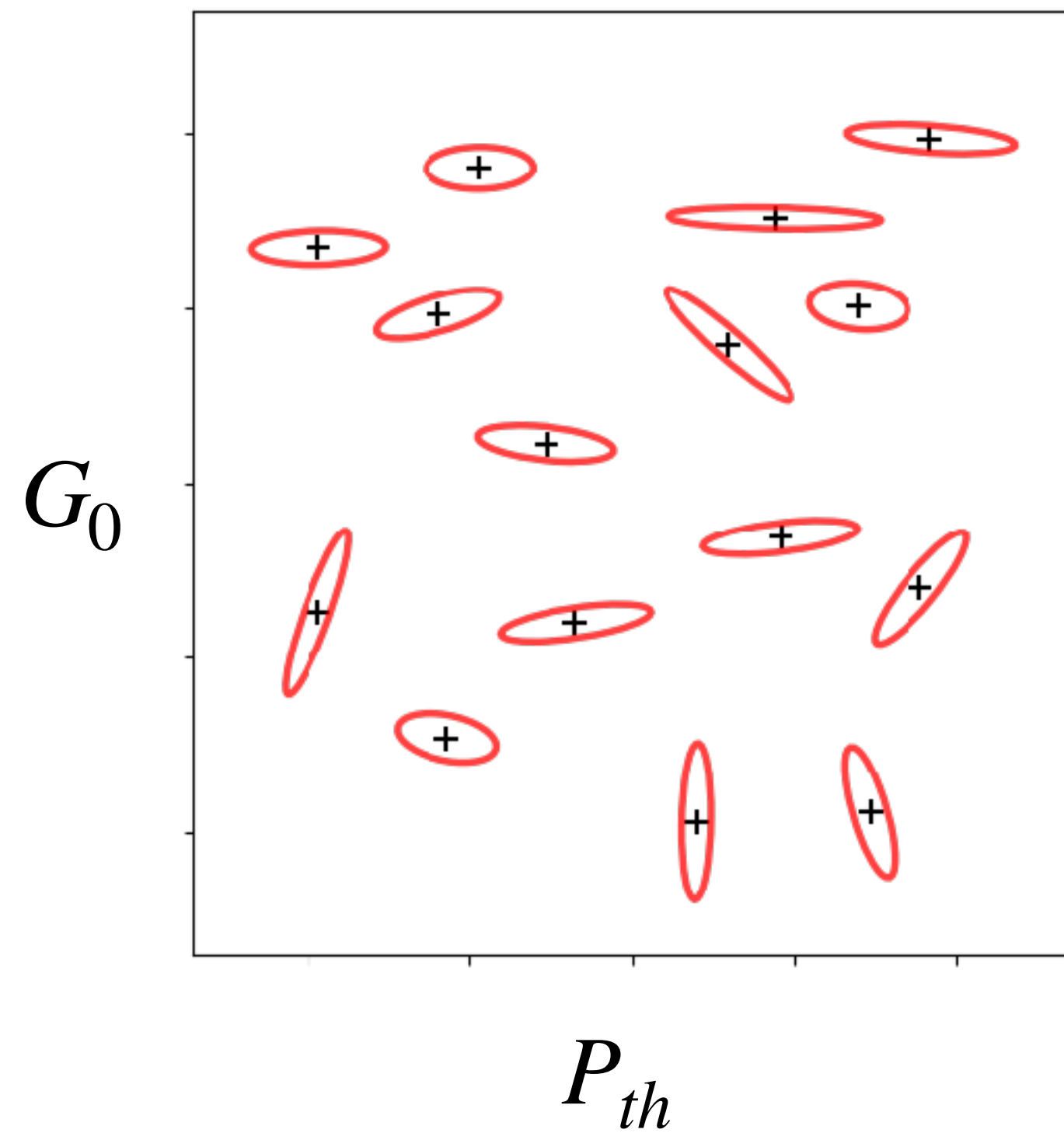


Smooth \implies Low penalty ✓



Markov Chain Monte Carlo

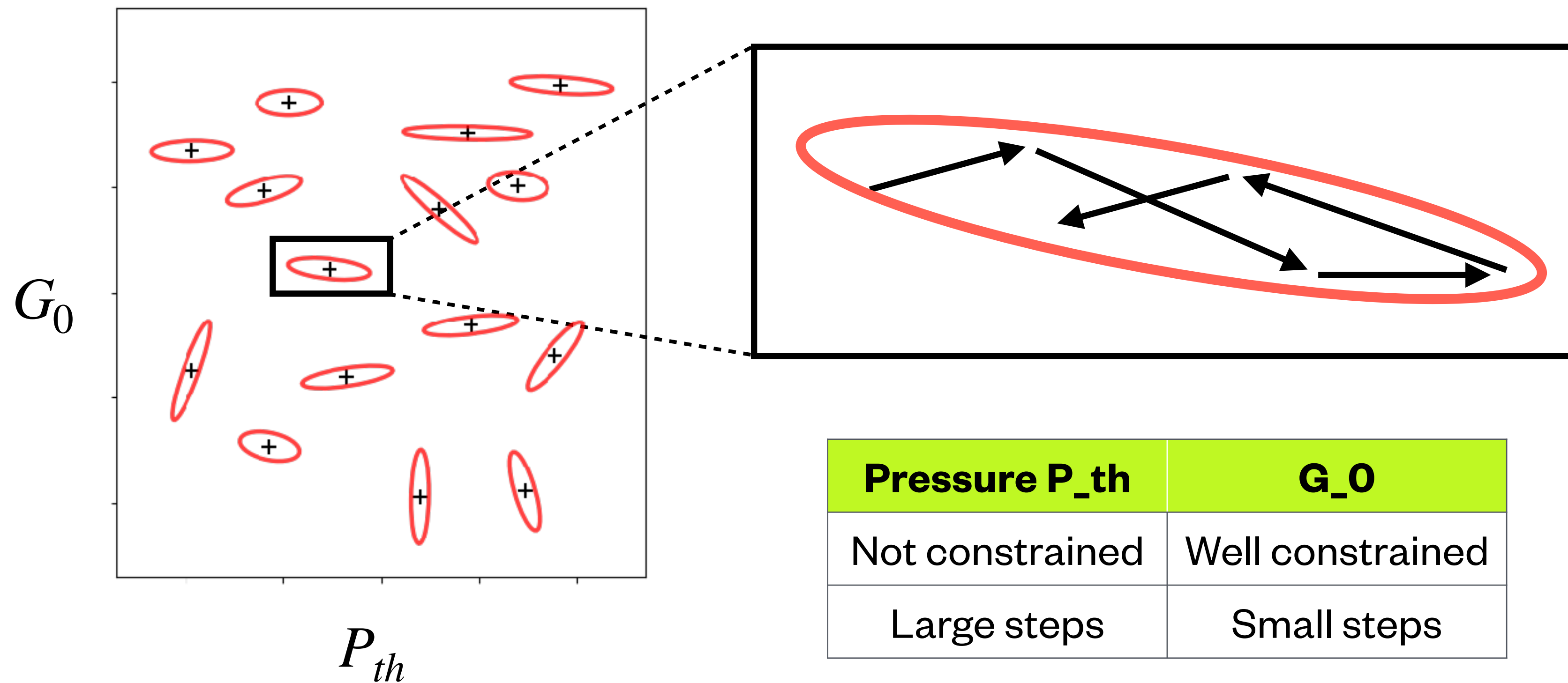
Some Gaussian Mixture
How to explore all modes?



Monte Carlo Markov Chain

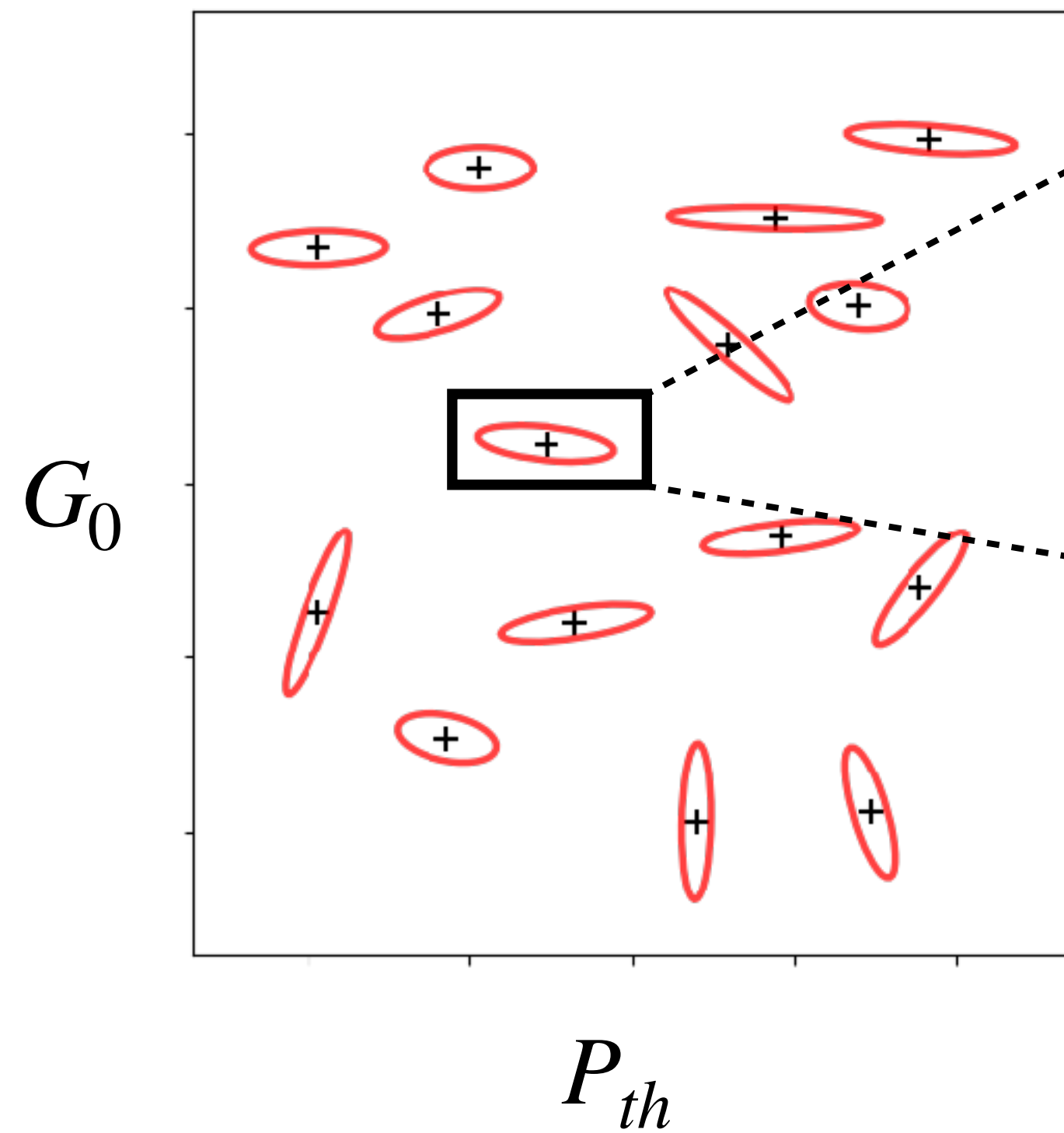
Some Gaussian Mixture
How to explore all modes?

PMALA transition kernel
Fast local exploration

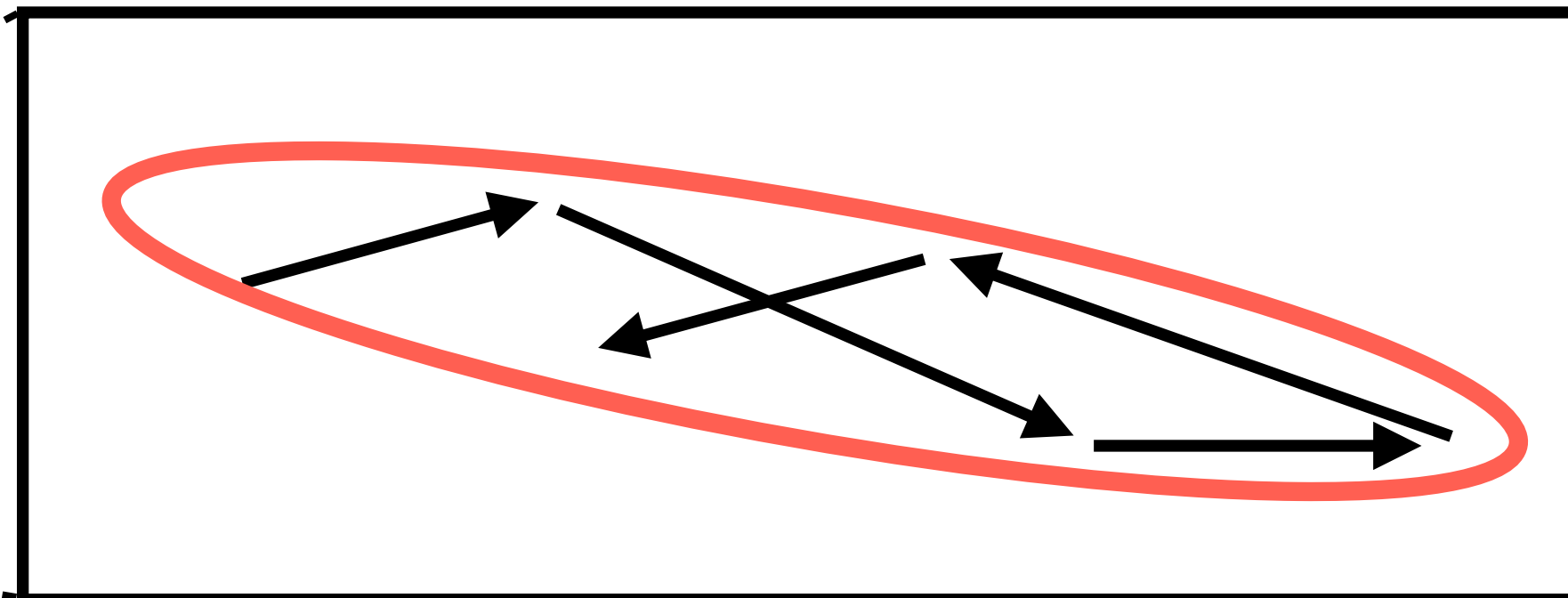


Monte Carlo Markov Chain

Some Gaussian Mixture
How to explore all modes?



PMALA transition kernel
Fast local exploration



Pressure P_{th}	G_0
Not constrained	Well constrained
Large steps	Small steps

MTM transition kernel
Jumps between modes

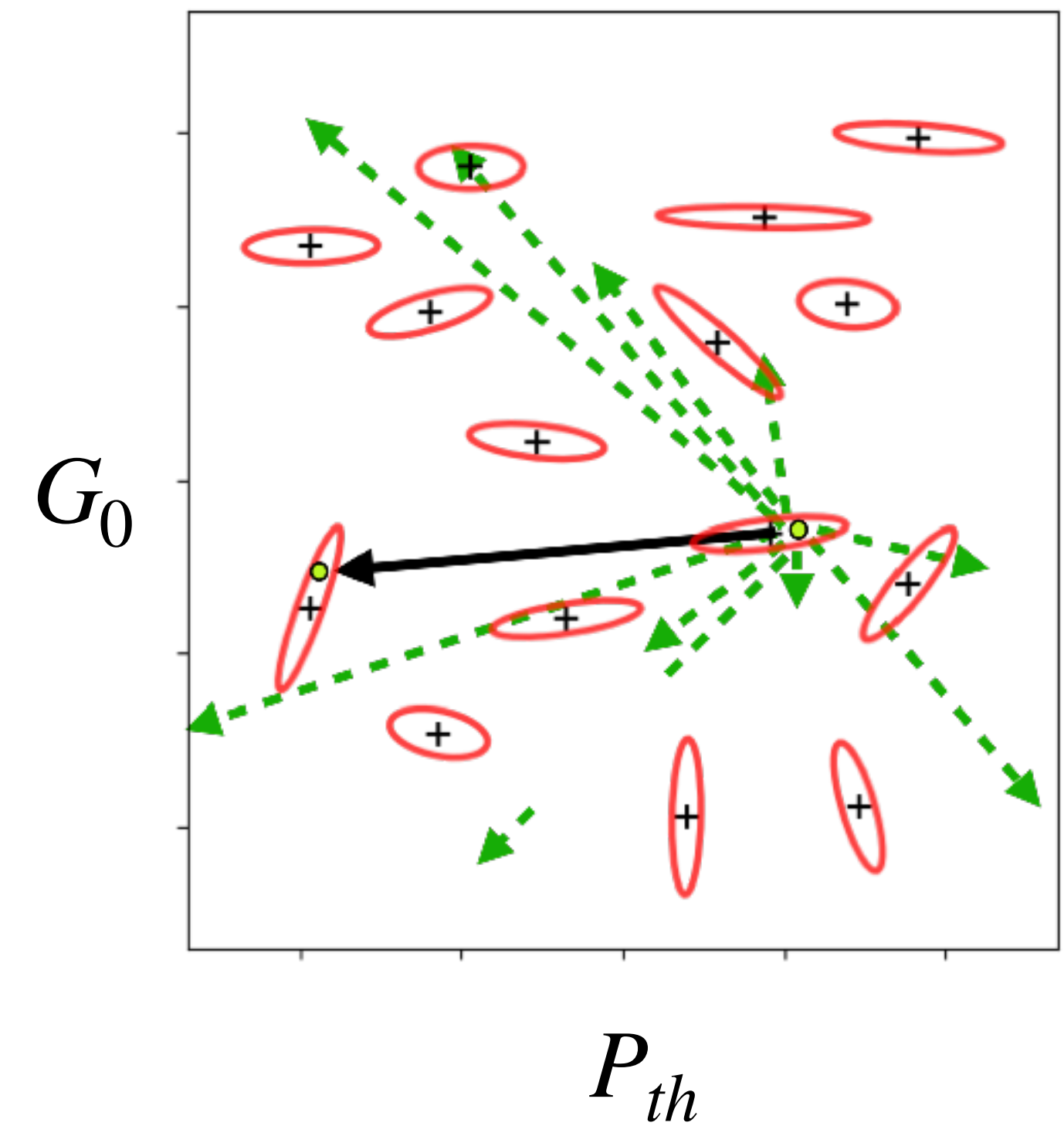
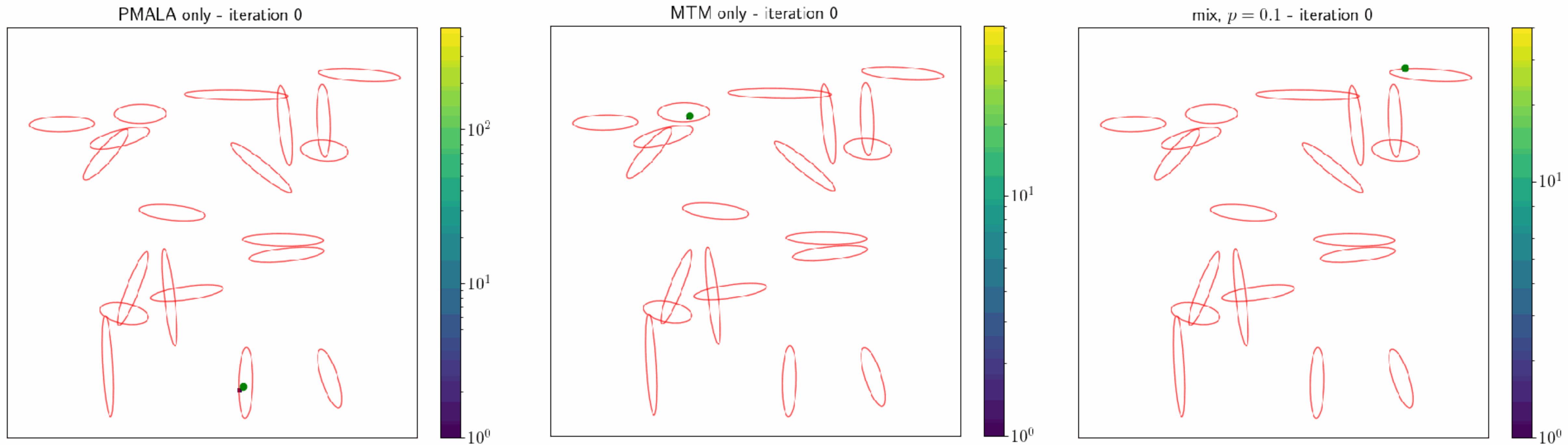
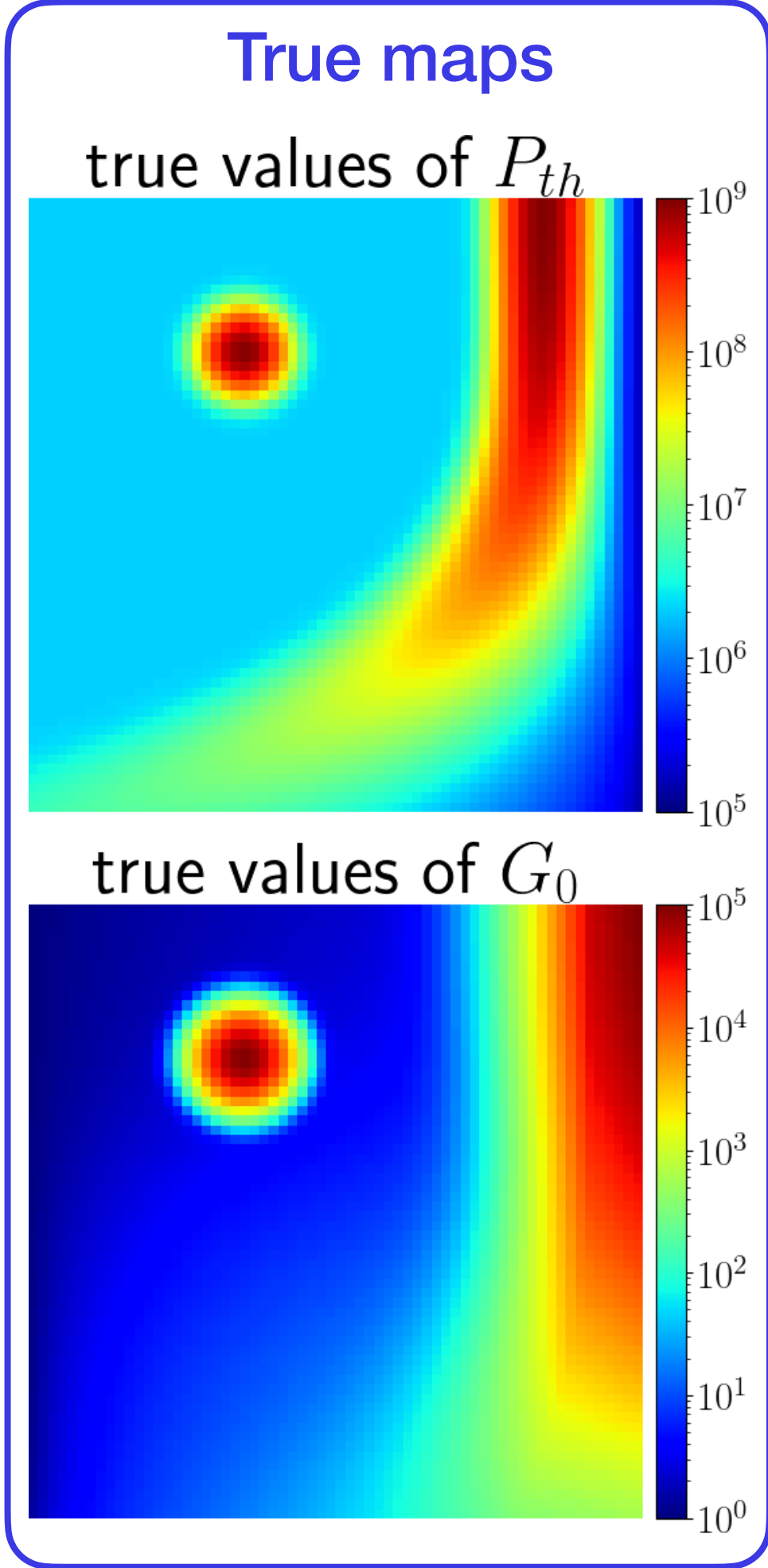


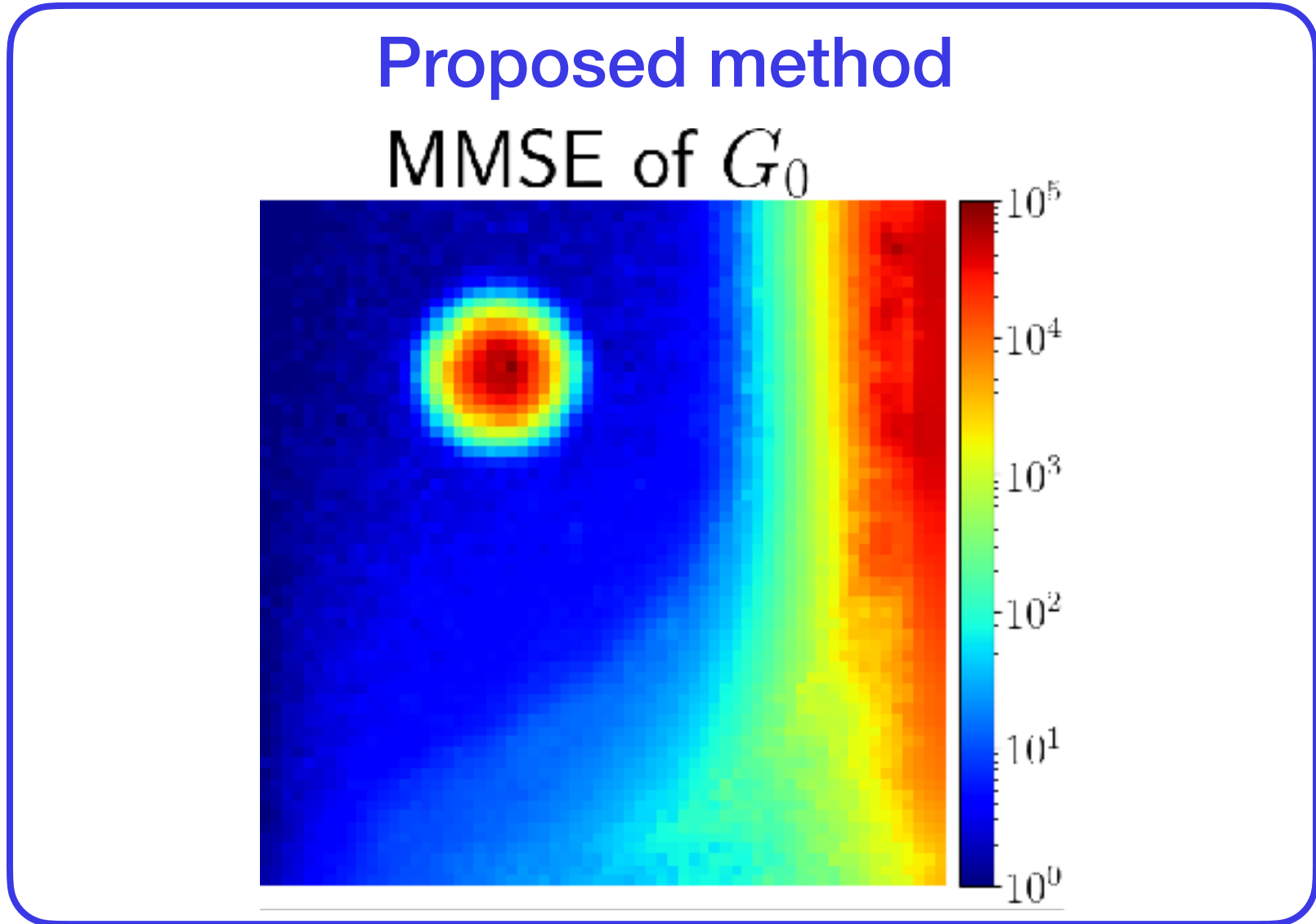
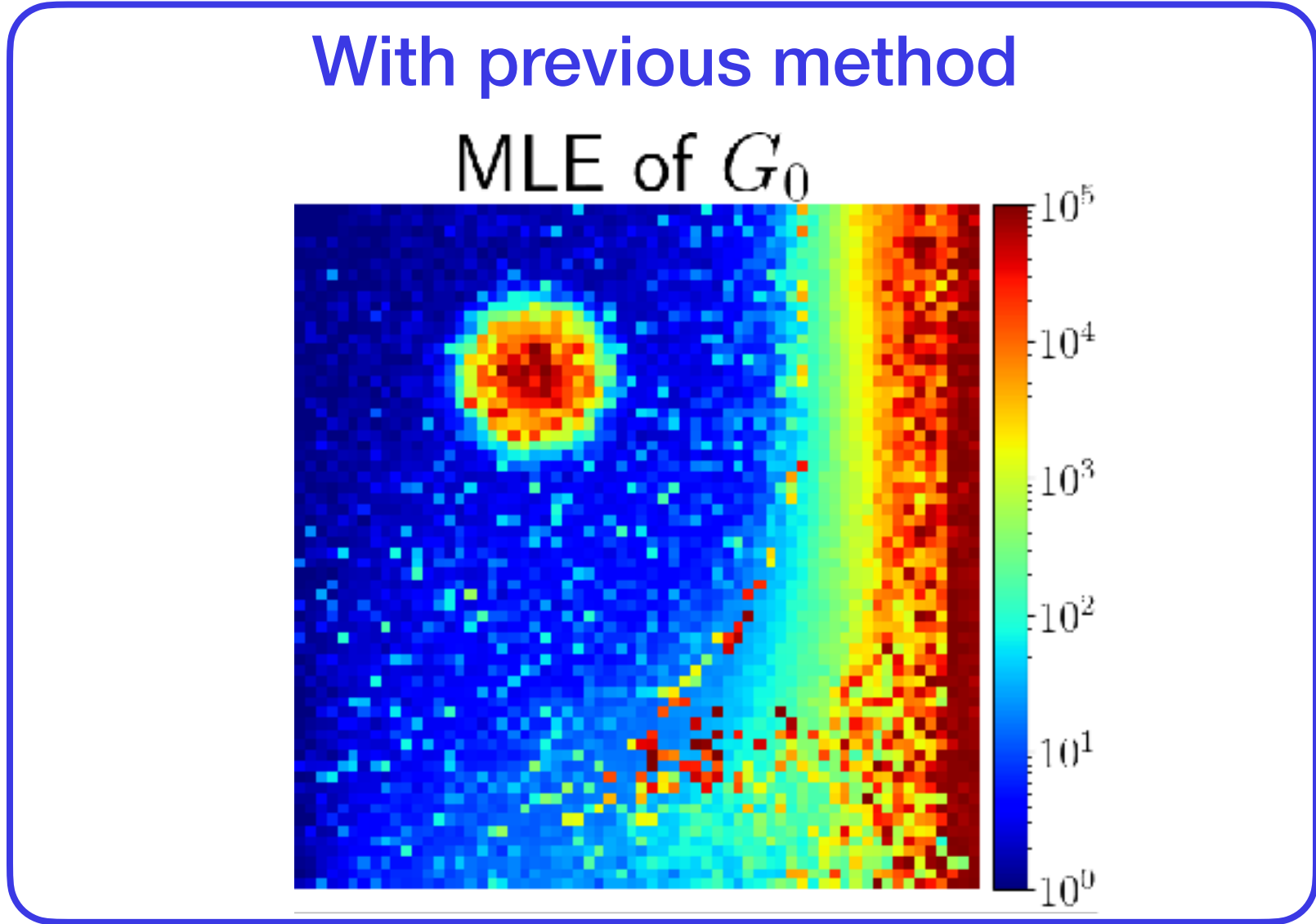
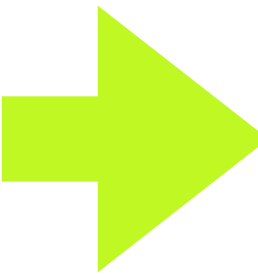
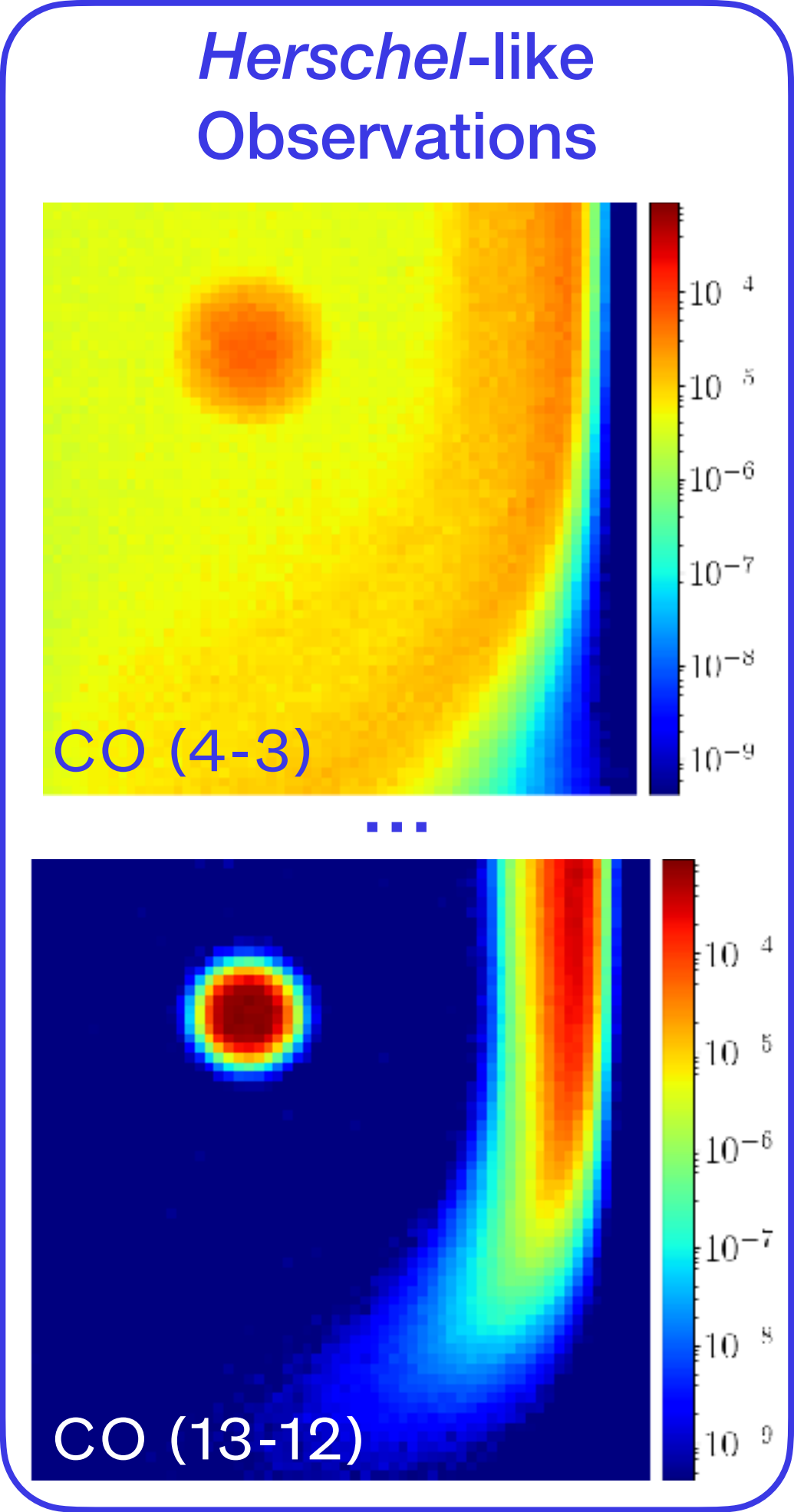
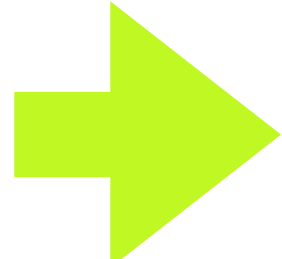
Illustration on Gaussian mixture



Synthetic PDR map



Meudon PDR
+
Noise



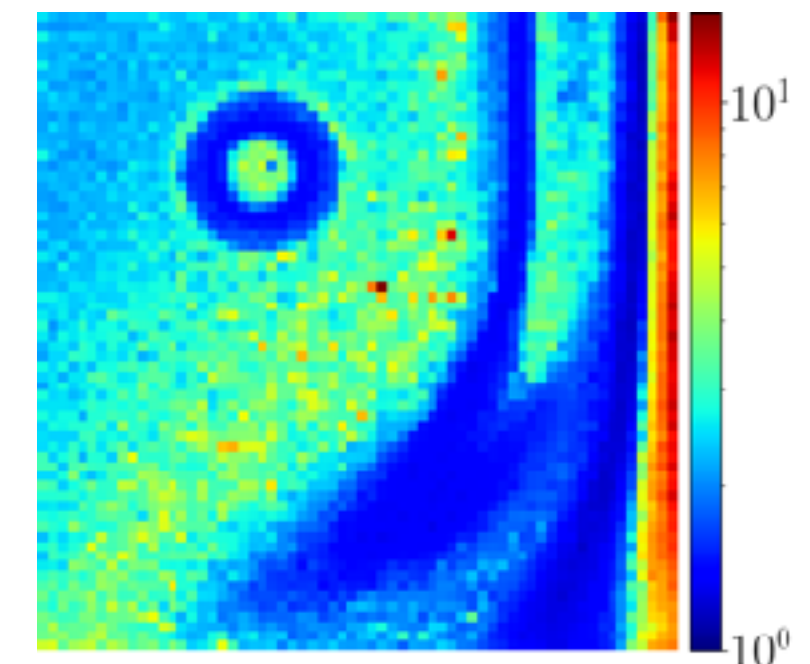
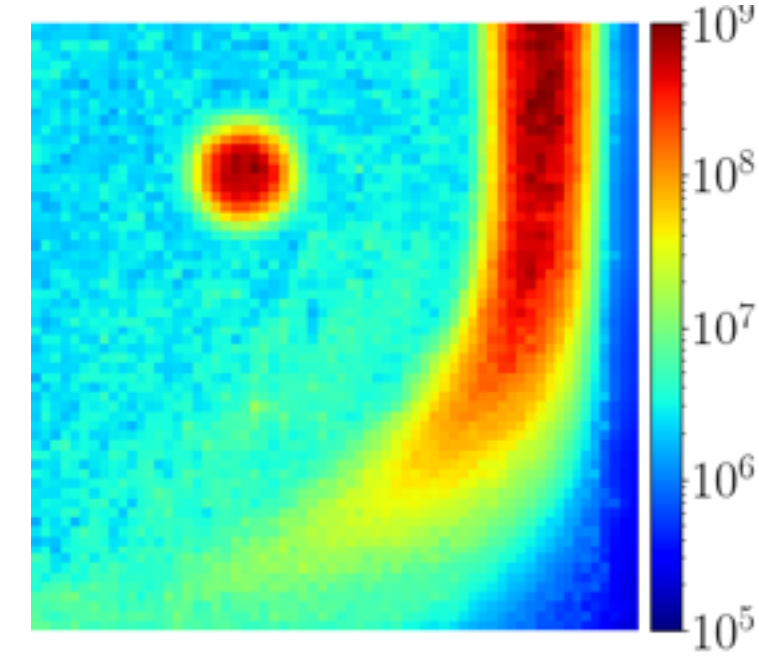
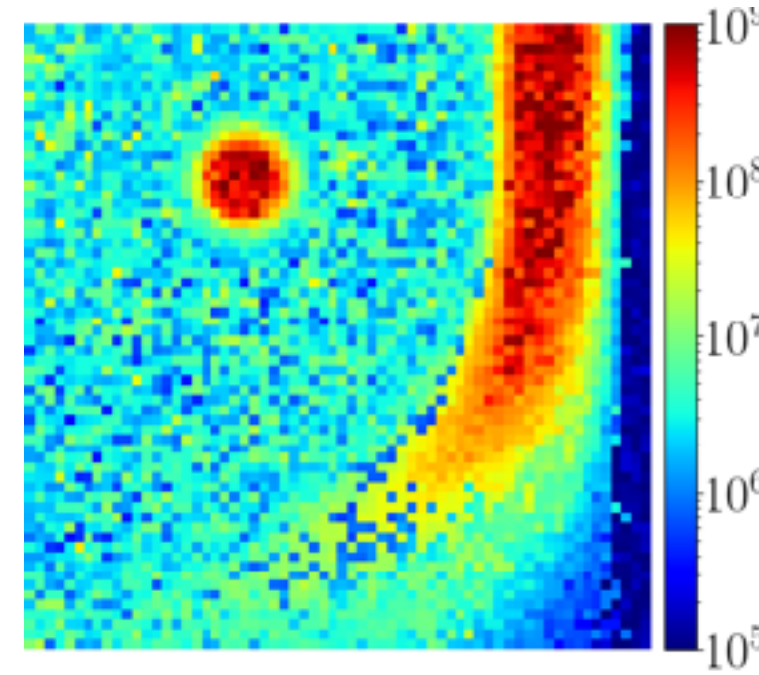
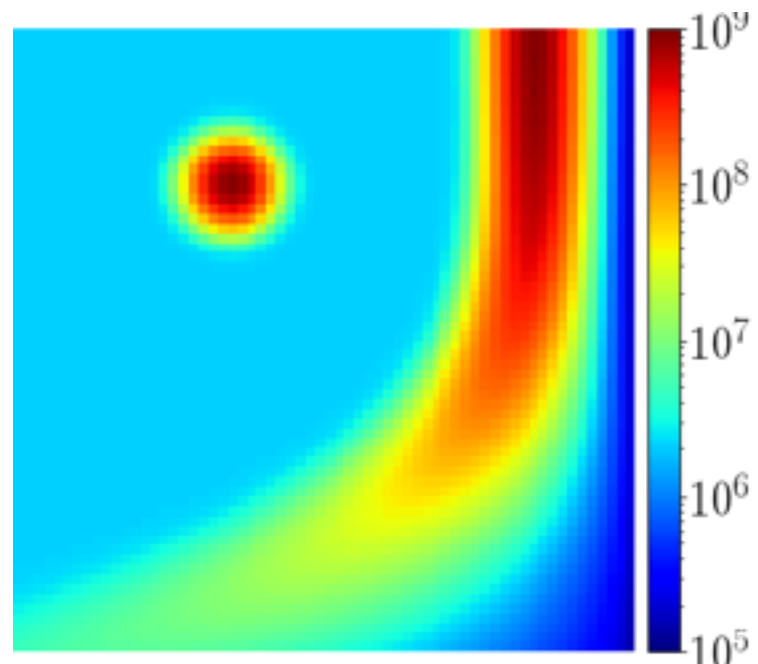
True values

Classic method

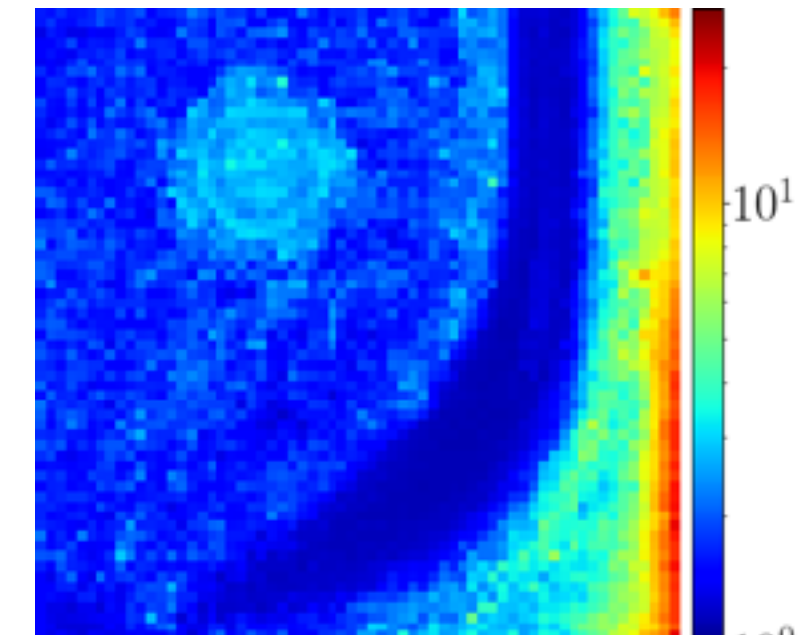
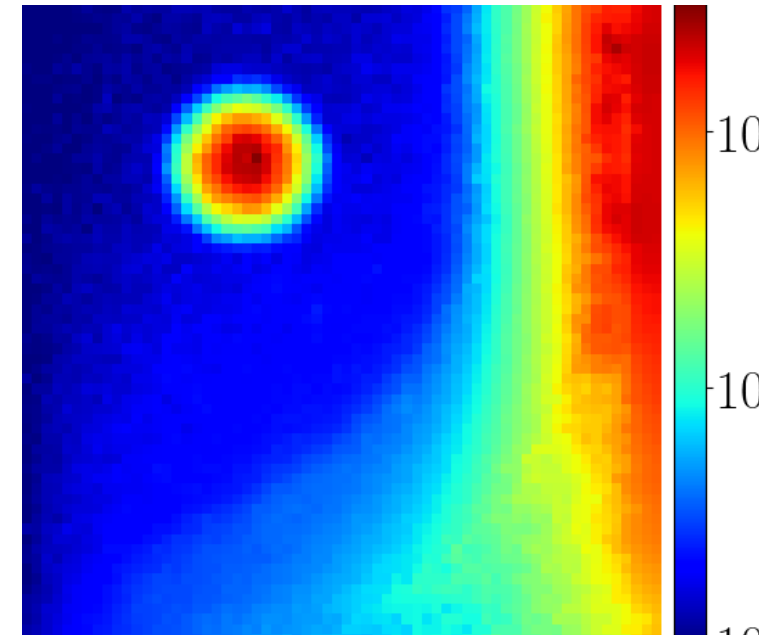
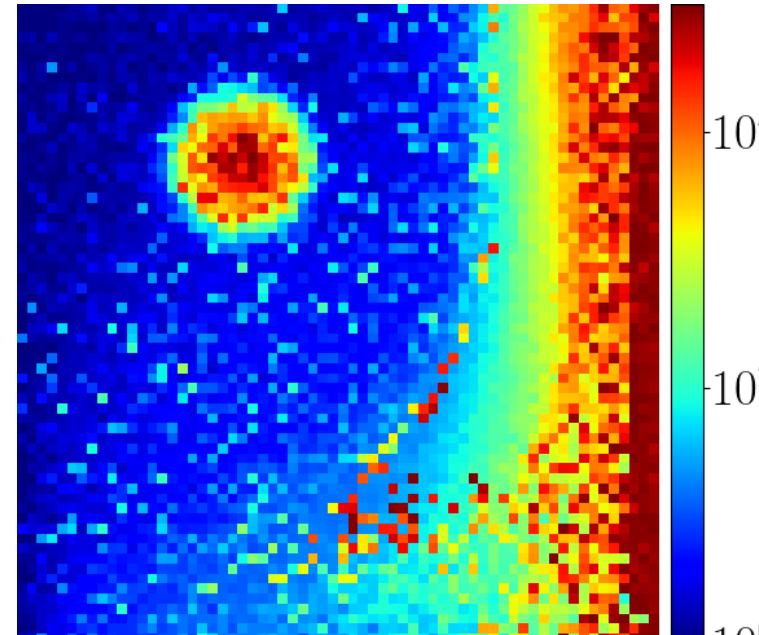
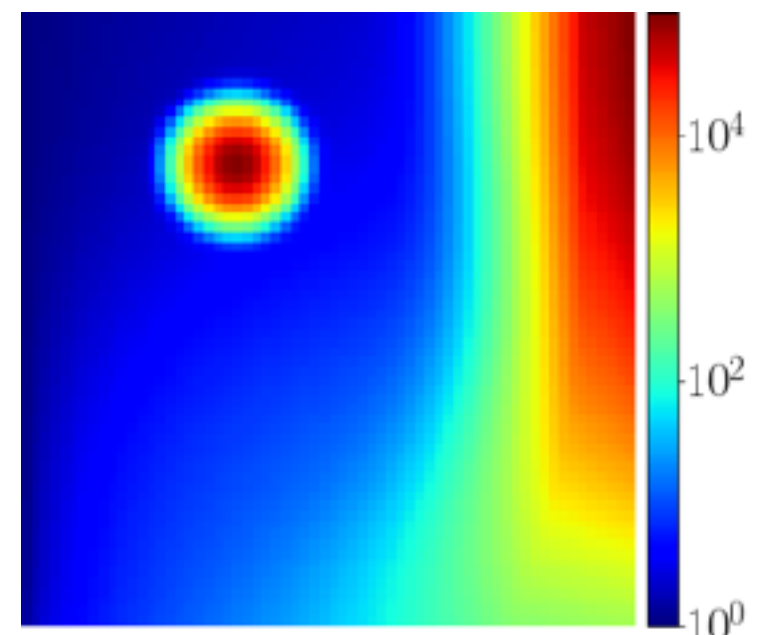
Proposed method

Credibility Intervals

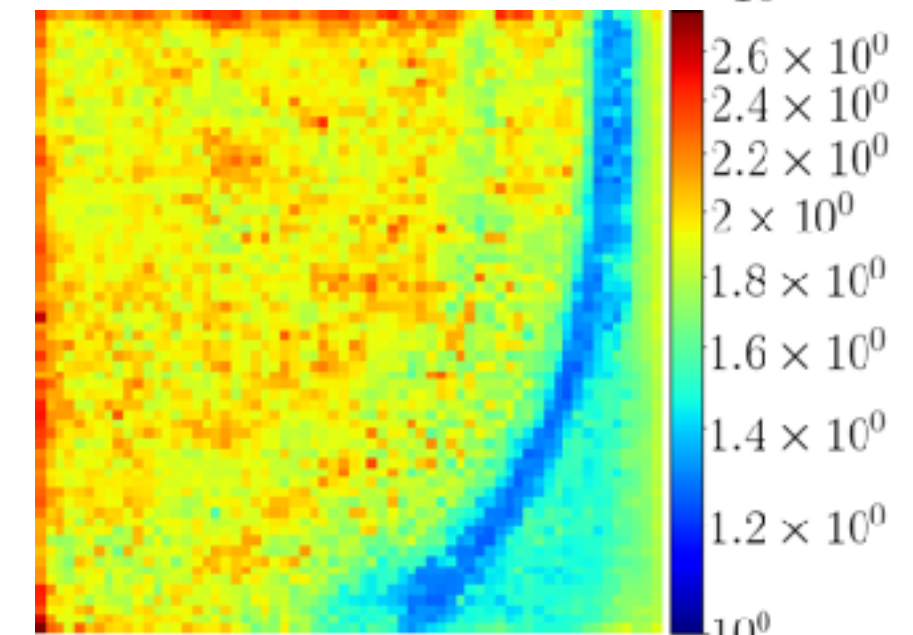
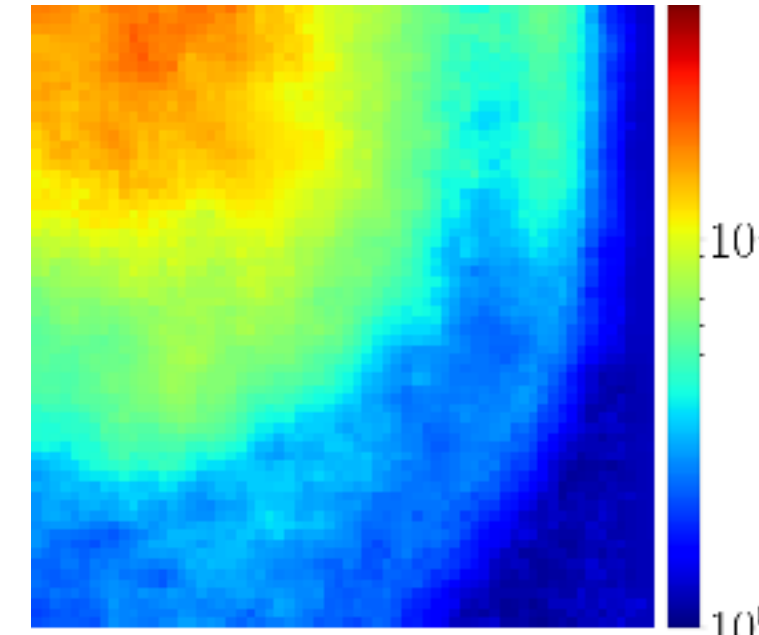
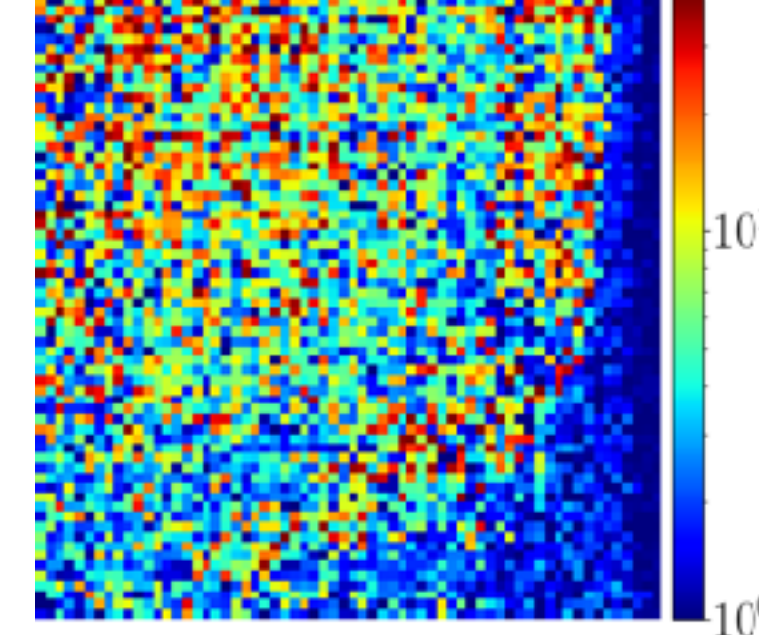
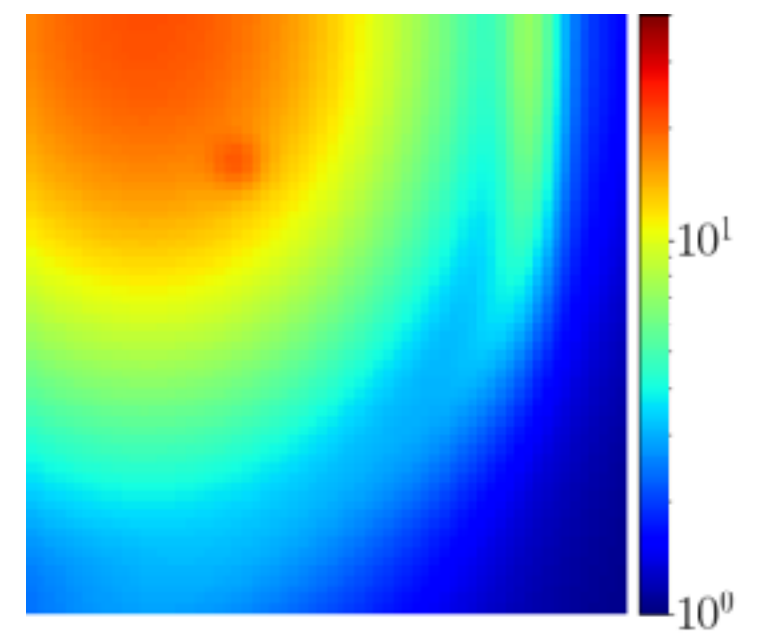
P_{th}



G_0



A_V



Application to real data: NGC 7023

One of the most studied PDR

Close to us (~ 320 pc)

Edge-on geometry

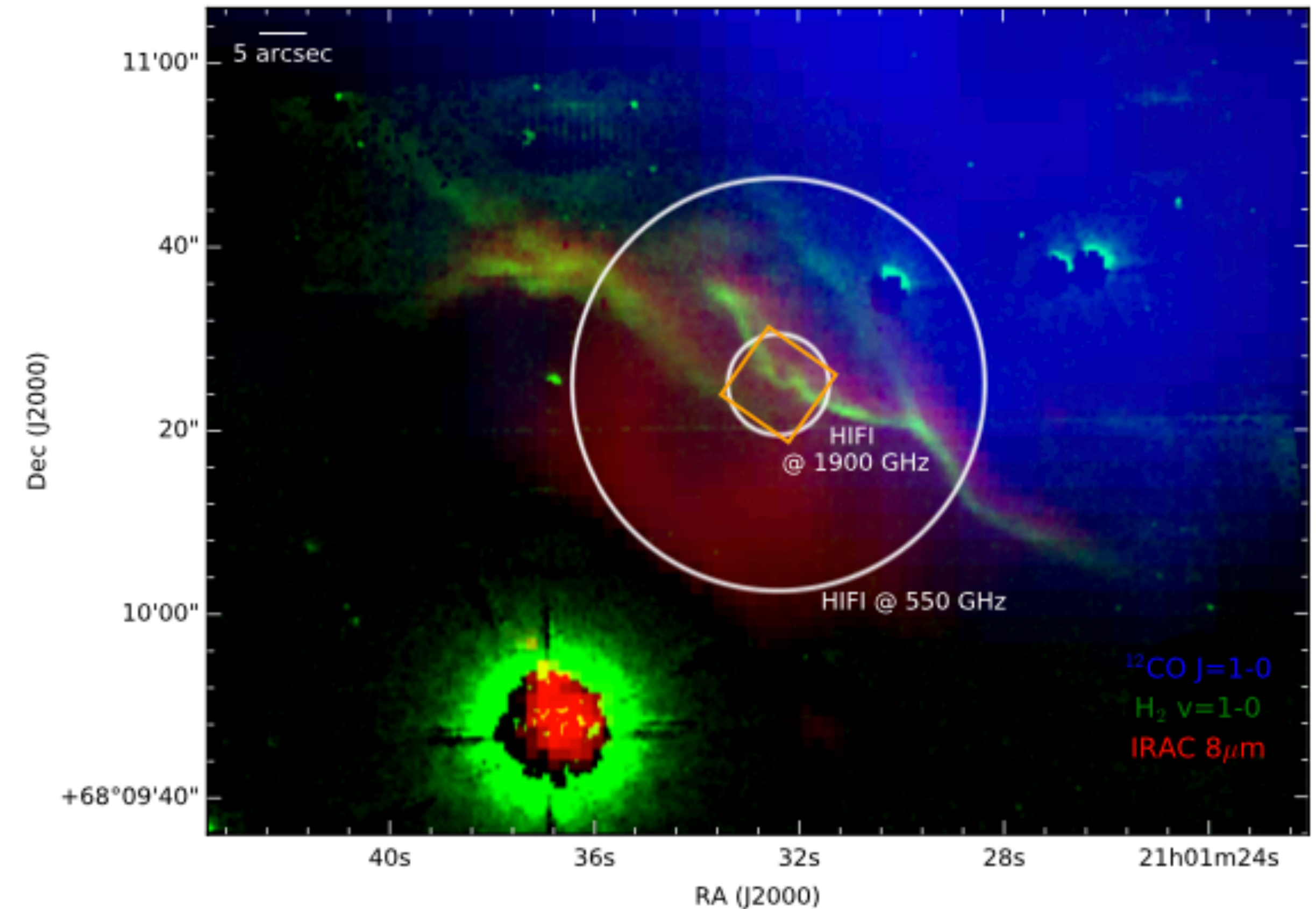
Illuminated by a spectroscopic binary system (B3Ve and B5)

Previous estimations:

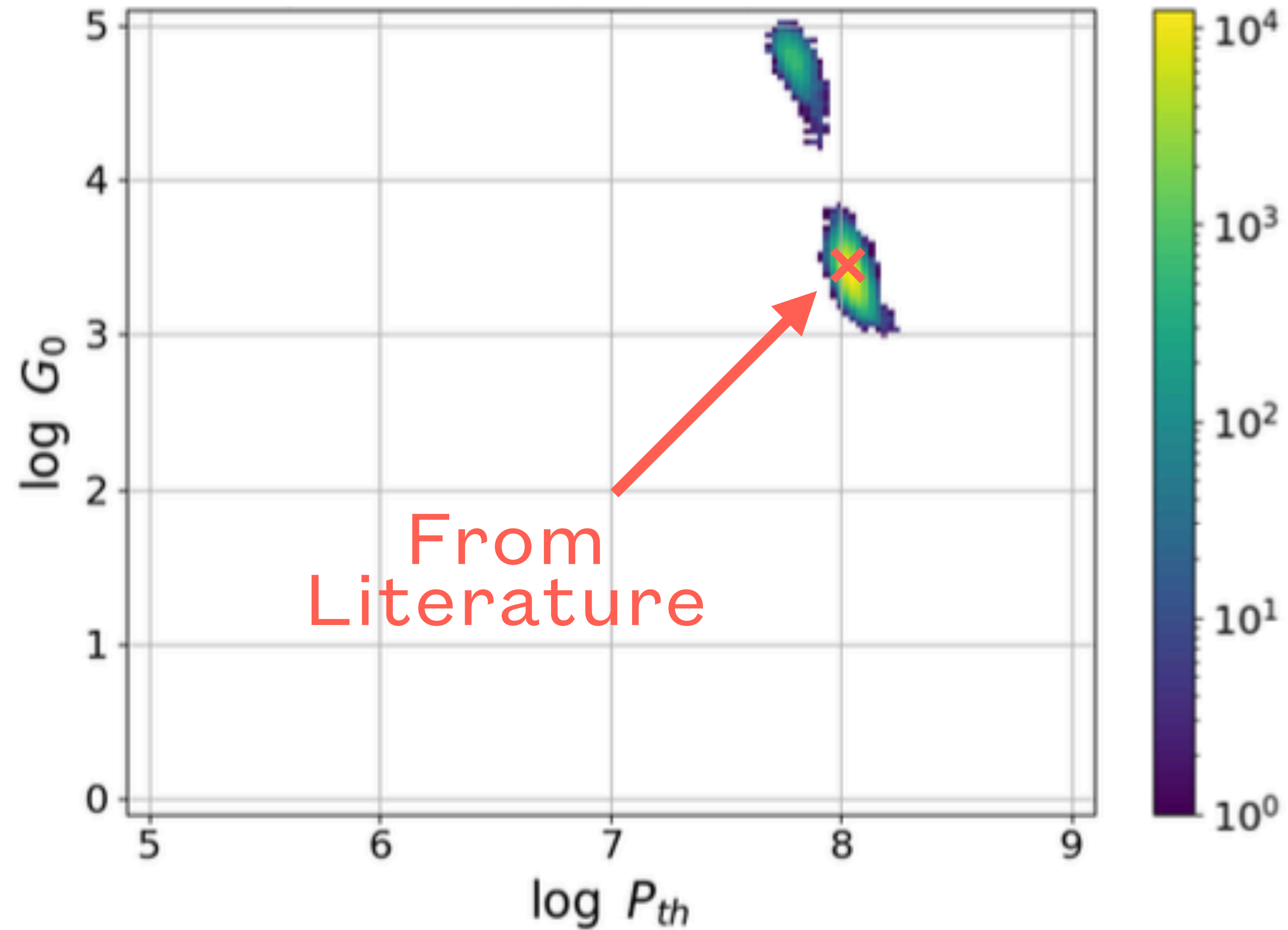
$G_0 \simeq 2600$ (Habing units) (Chokshi et al., 1988)

$P_{th} \simeq 10^8 \text{ K cm}^{-3}$ (Joblin et al., 2018)

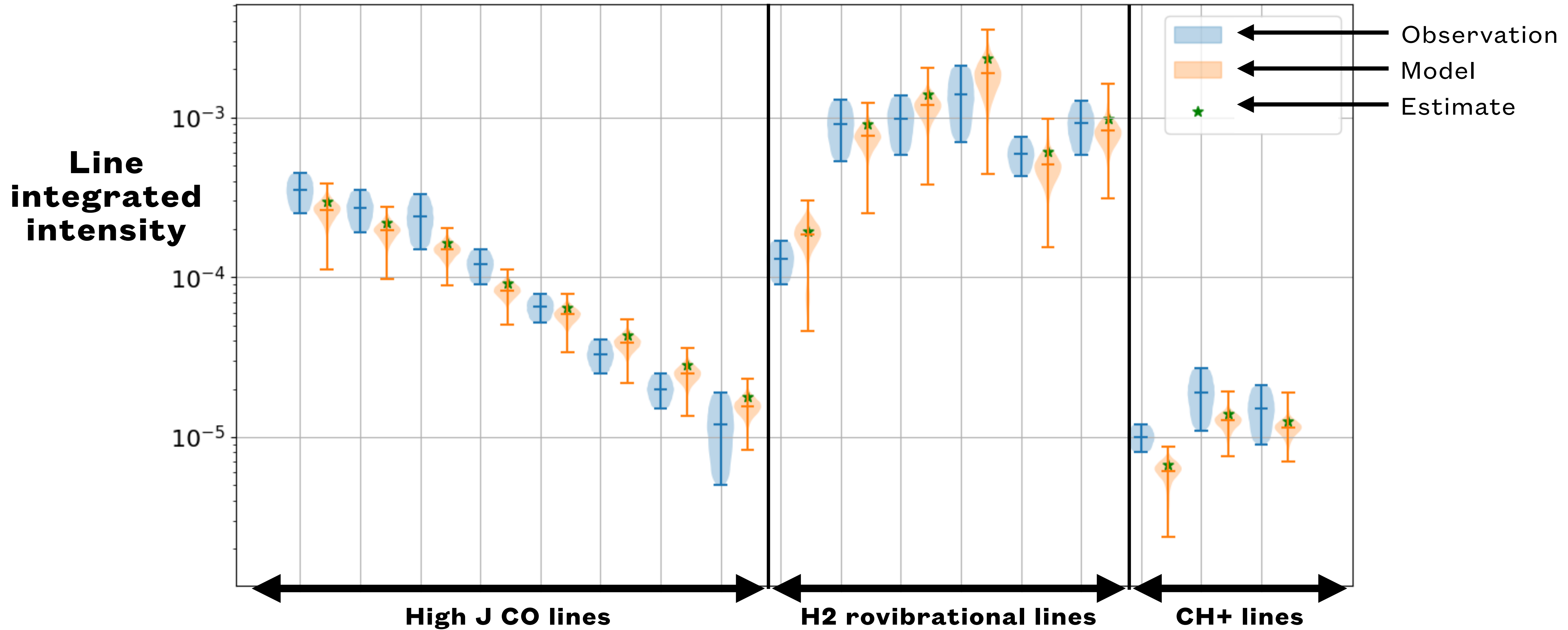
$A_V^{tot} \simeq 10$ mag (Joblin et al., 2018)



Sampling results

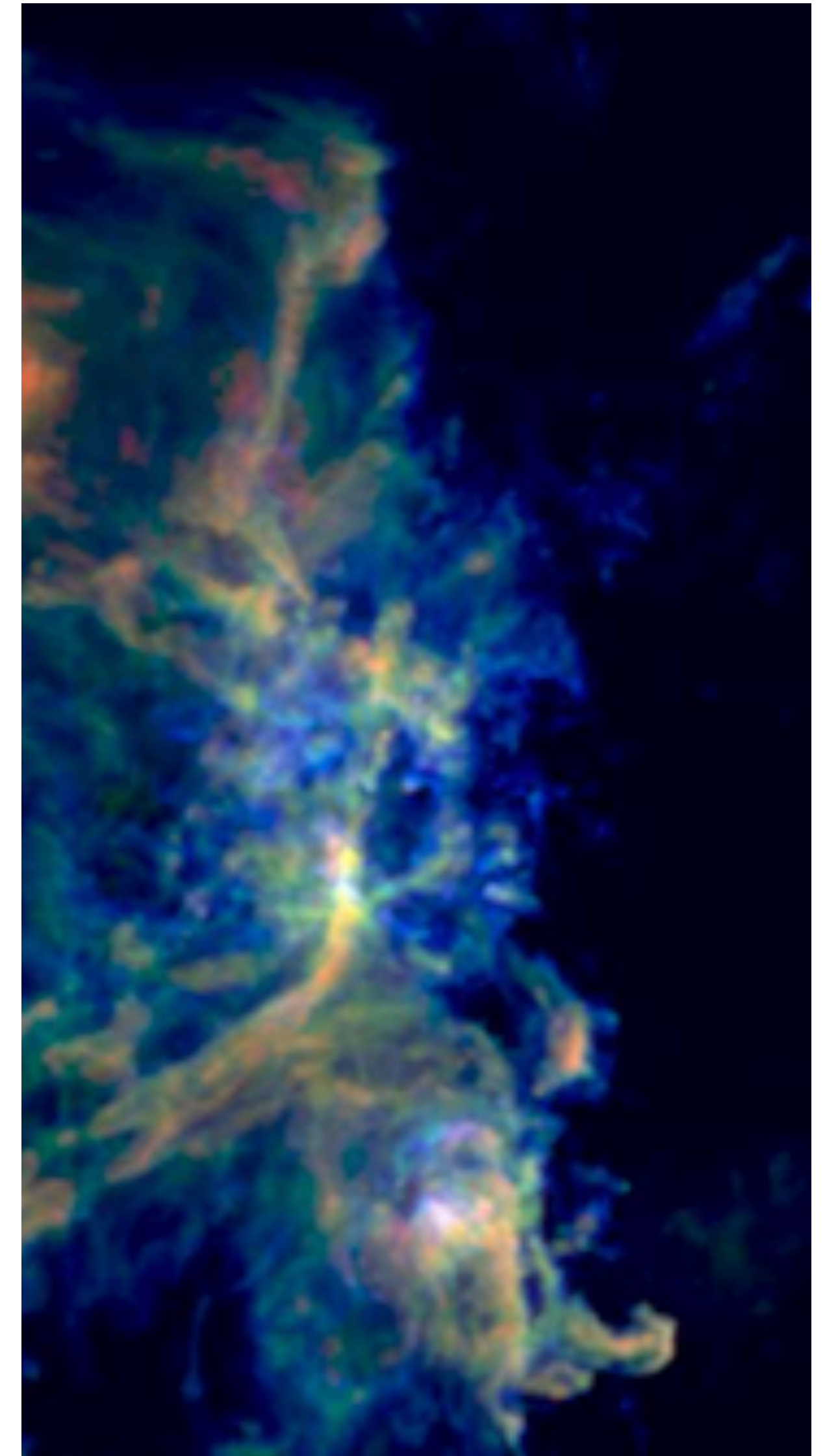


Reconstruction of observations



Conclusion

- New tool ready to be used! \implies will be available on ism.obspm.fr
 - **Spatial regularization** \rightarrow enforces spatial smoothness
 - **Bayesian approach** \rightarrow provides both estimates and credibility intervals
- Applications:
 - synthetic case with 4096 pixels ✓
 - NGC 7023 (1 pixel) ✓
 - Real data (Horse Head, $\simeq 10^3$ pixels / Orion B $\simeq 10^6$ pixels)
 - JWST observations



Appendix

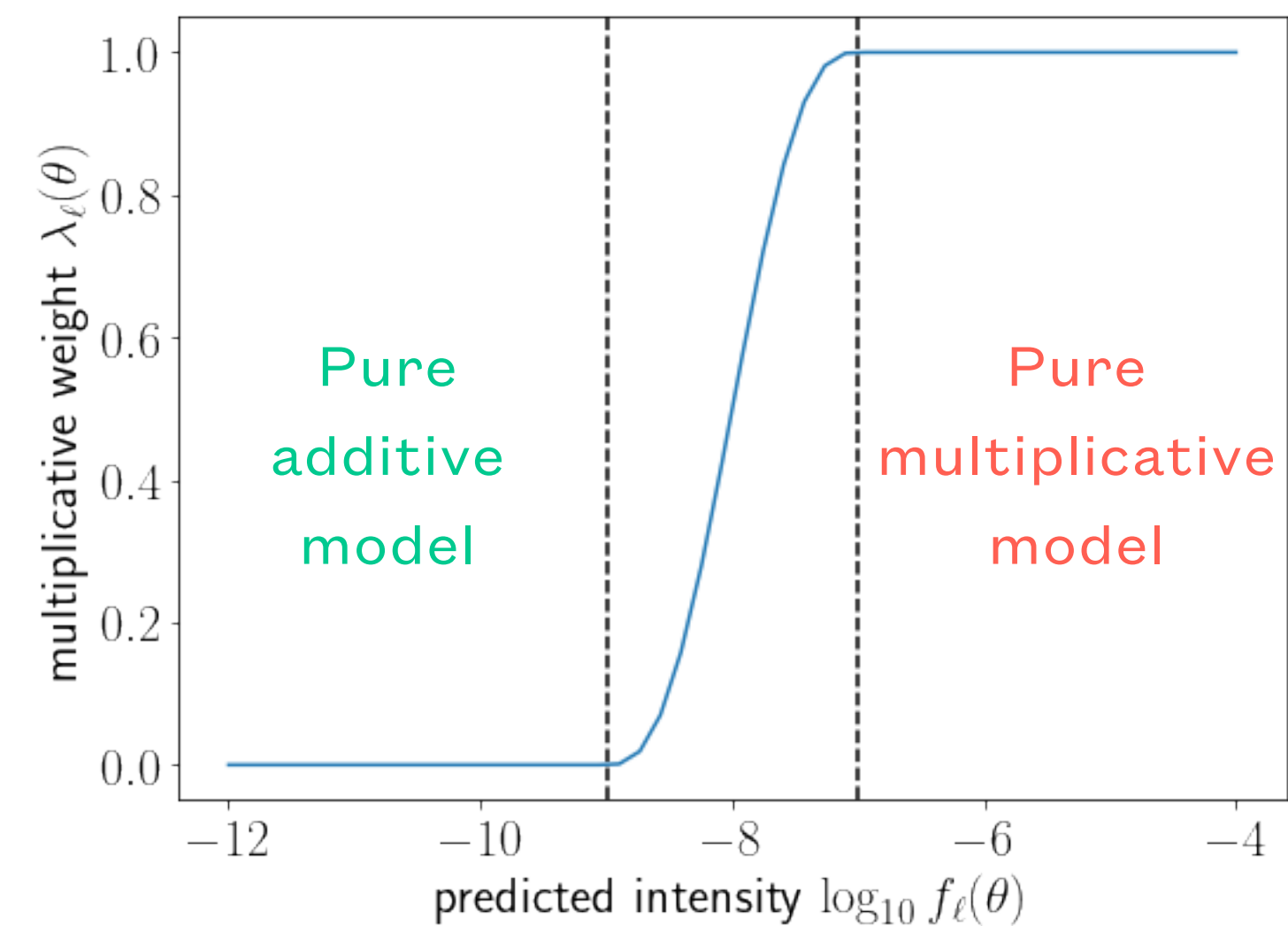
Some formulae

Spatial prior

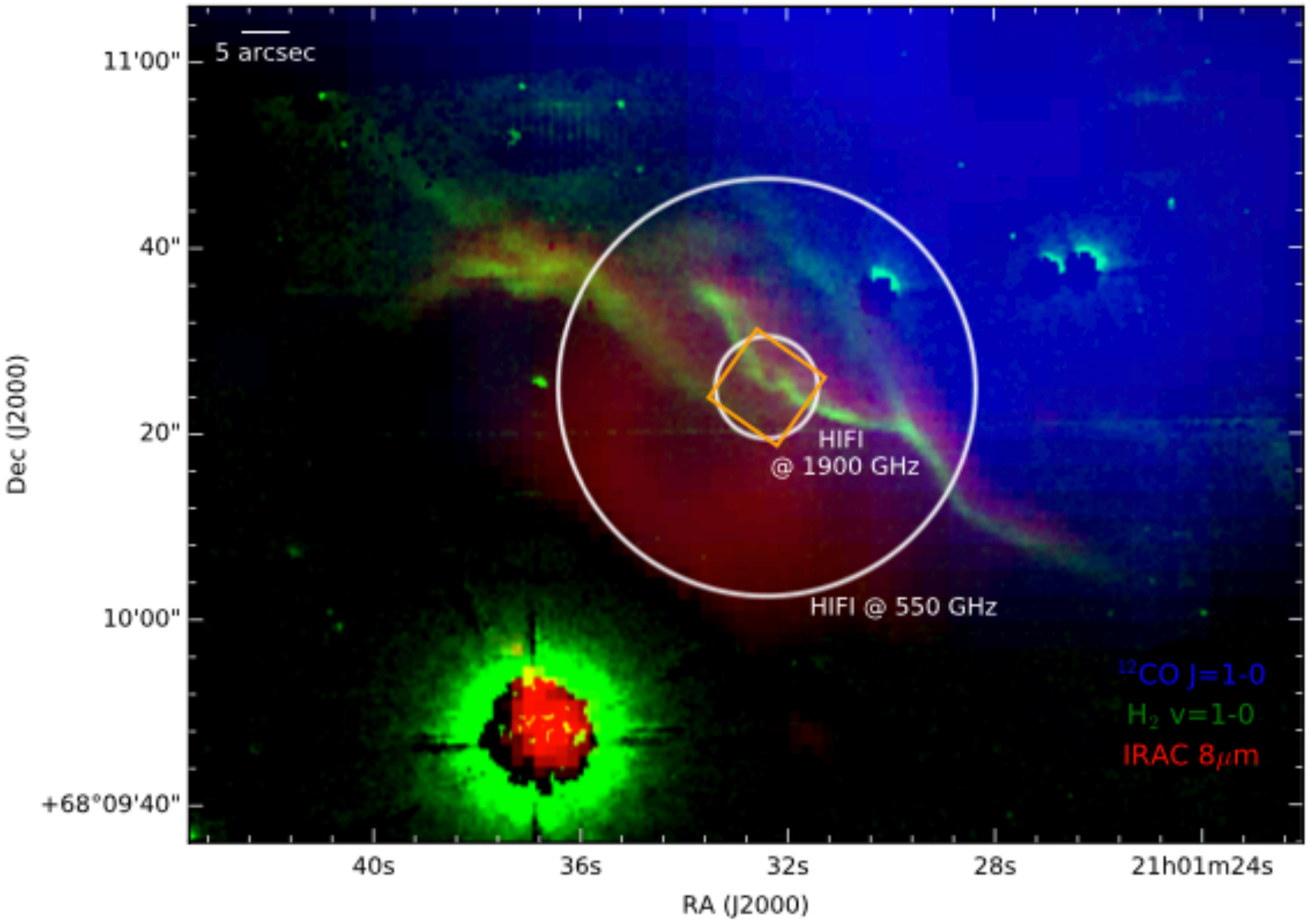
$$\|\Delta\Theta_{.d}\|_2^2 = \sum_{n=1}^N \sum_{i \in V_n} (\theta_{n,d} - \theta_{i,d})^2$$

Likelihood approximation

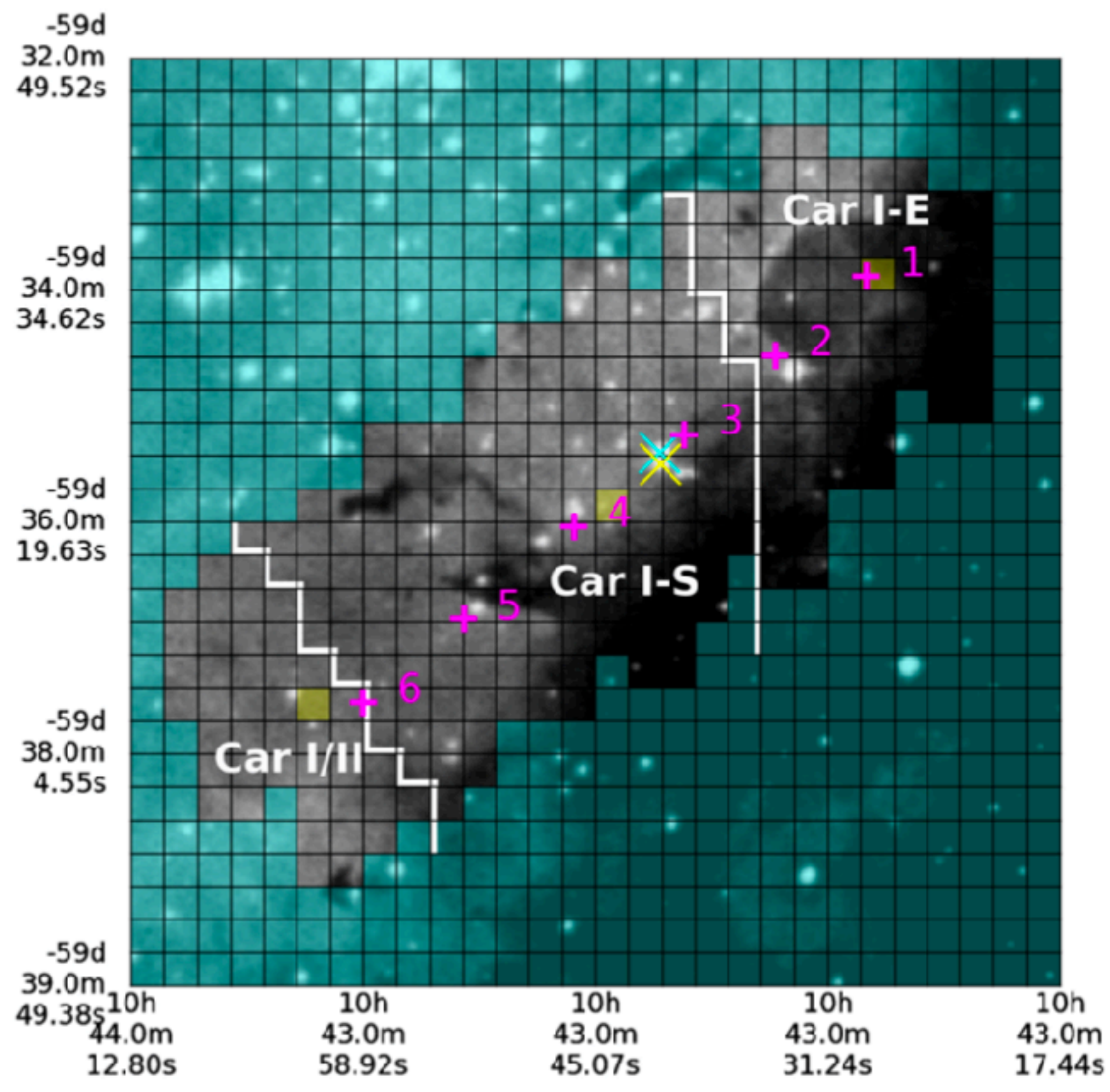
$$\begin{aligned} \tilde{\pi}(y_{n,\ell} | \theta_n) &\propto \left[\pi^{(a)}(y_{n,\ell} | \theta_n)^{1-\lambda(\theta_n)} \pi^{(m)}(y_{n,\ell} | \theta_n)^{\lambda(\theta_n)} \right]^{1-c_{n,\ell}} \\ &\times \left[F^{(a)}(\omega | \theta_n)^{1-\lambda(\theta_n)} F^{(m)}(\omega | \theta_n)^{\lambda(\theta_n)} \right]^{c_{n,\ell}} \end{aligned}$$



Classic observations: $10^0 - 10^2$ pixels

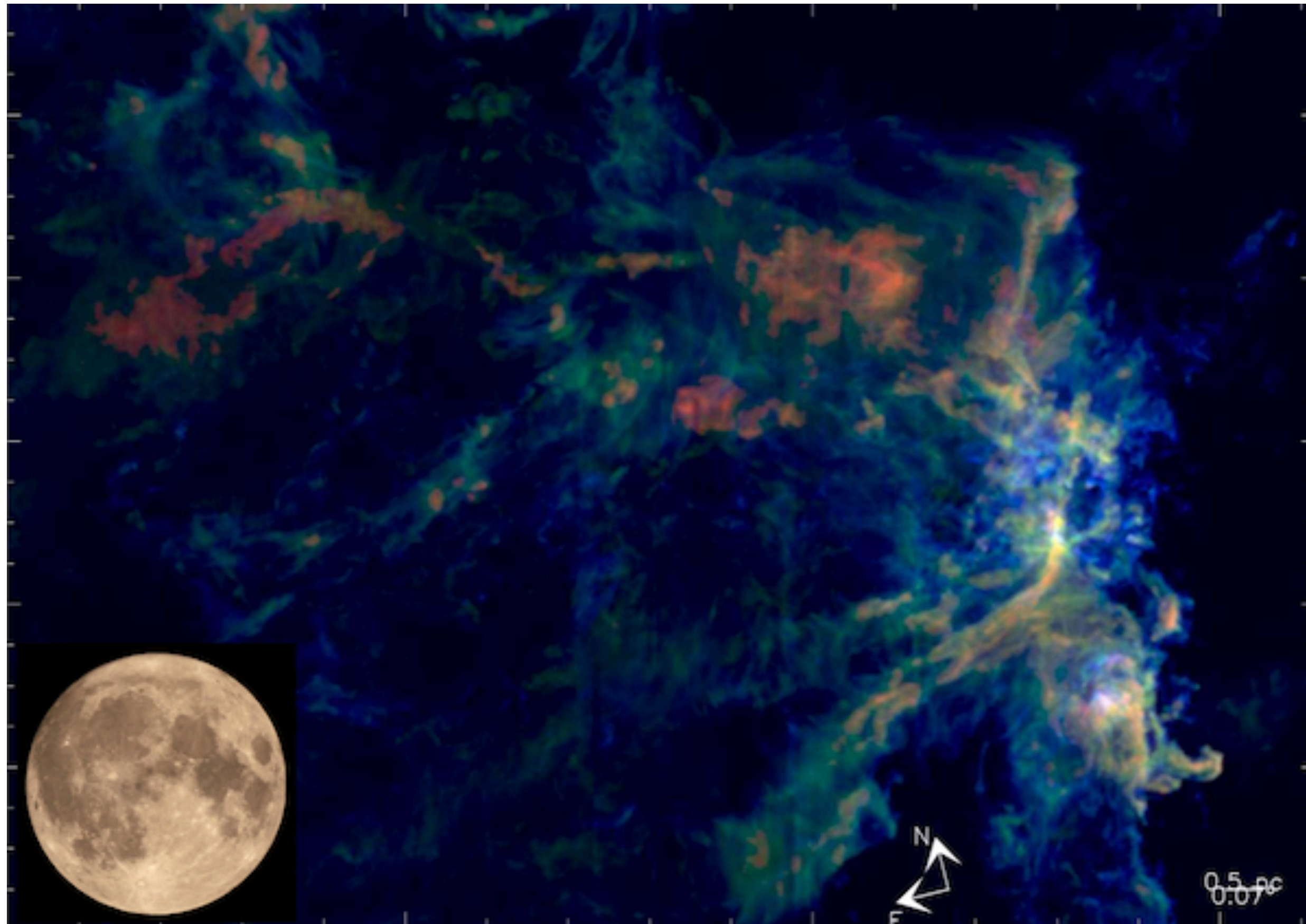


(Joblin et al., 2018)



(Wu et al., 2018)

Wider maps: towards $10^3 - 10^6$ pixels



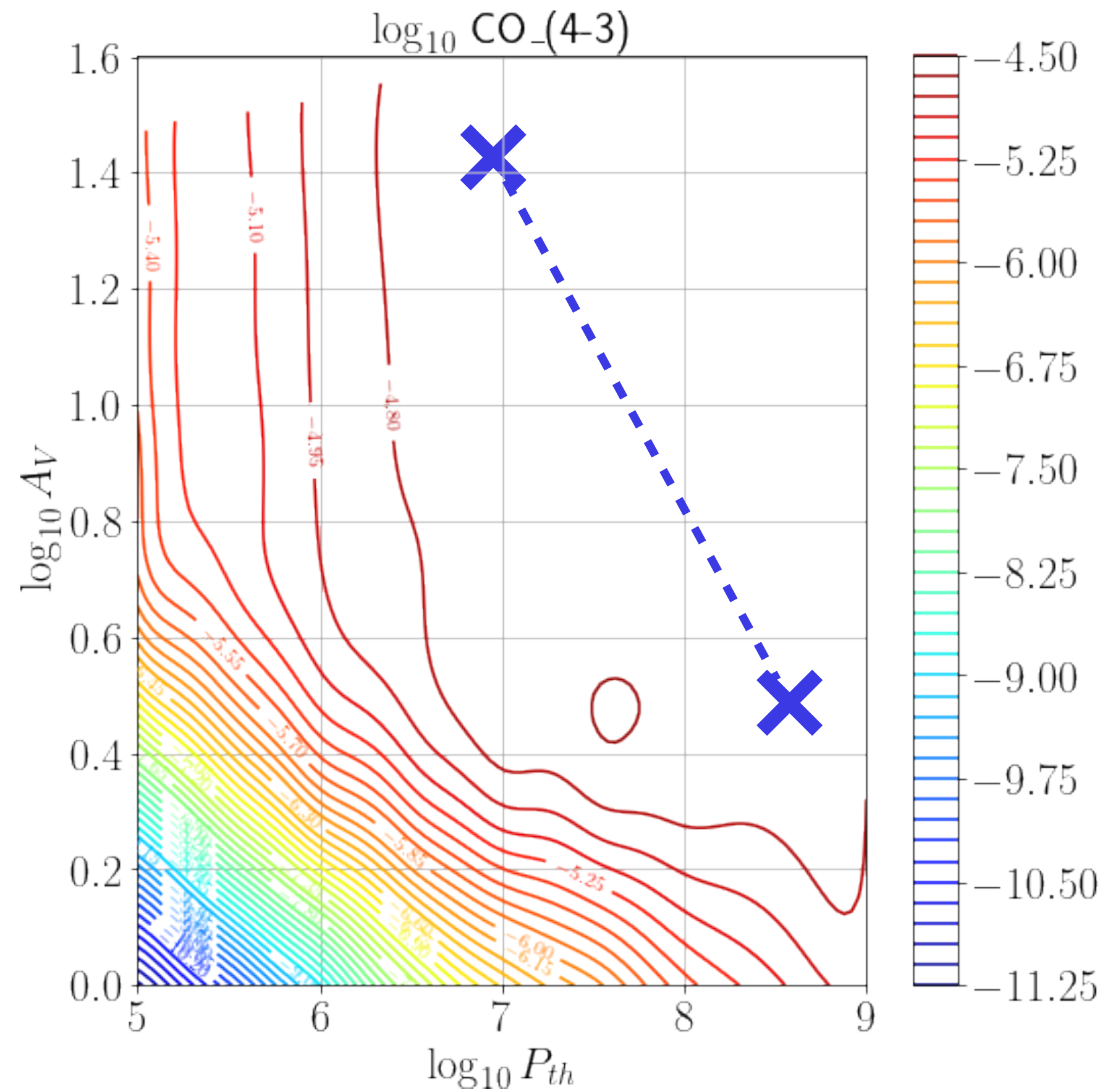
Source: [https://www.esa.int/ESA_Multimedia/Sets/Webb_First_Images/\(result_type\)/images](https://www.esa.int/ESA_Multimedia/Sets/Webb_First_Images/(result_type)/images)



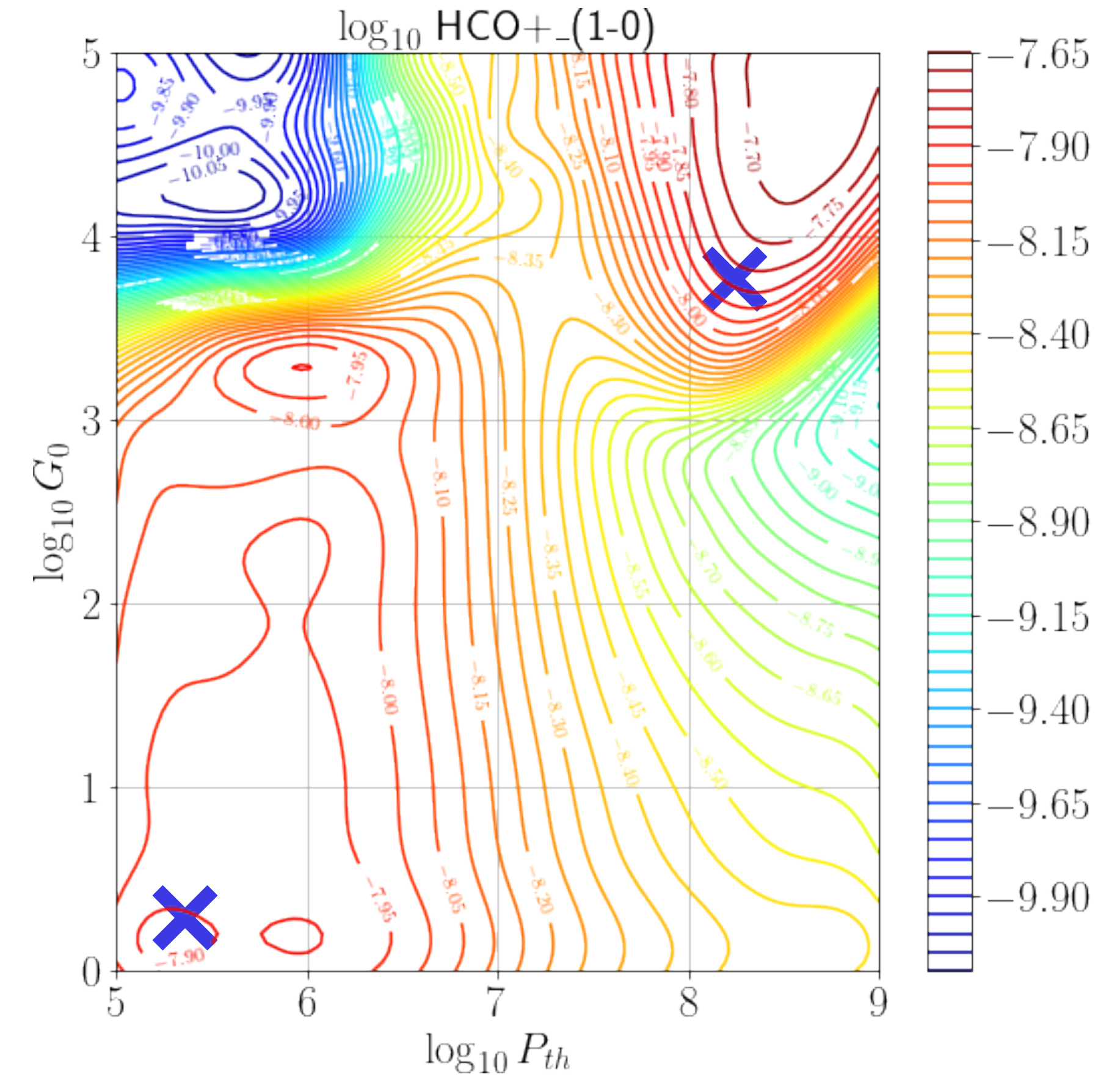
Source: [https://www.esa.int/ESA_Multimedia/Sets/Webb_First_Images/\(result_type\)/images](https://www.esa.int/ESA_Multimedia/Sets/Webb_First_Images/(result_type)/images)

Degeneracies and multimodality

Saturation of CO lines with AV



Multimodality with HCO+



Identical observations

comparison of $f(x)$ and y distributions

